



Modern Robotics: Evolutionary Robotics

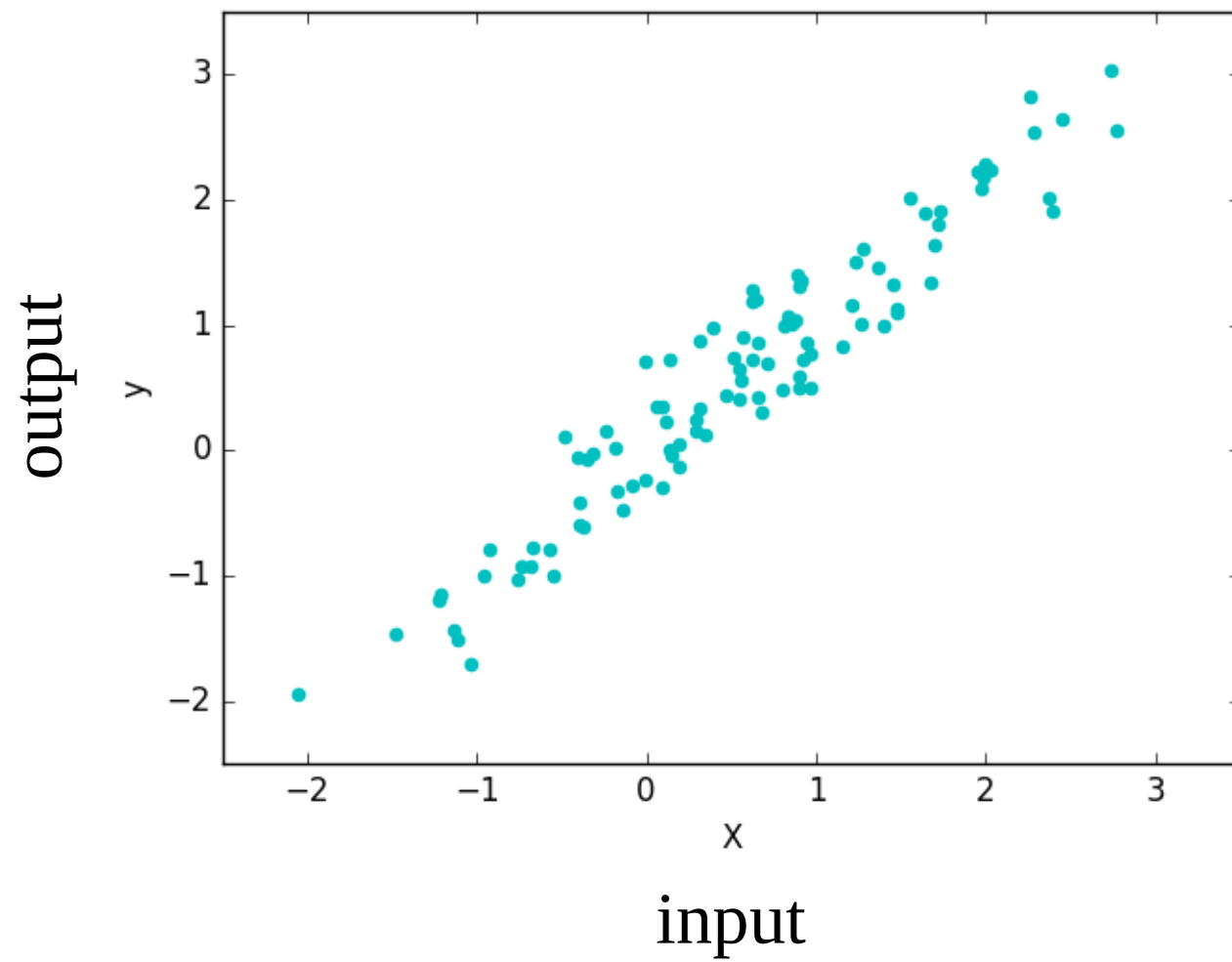
COSC 4560 / COSC 5560

Professor Cheney
4/16/18

Other Ways to Train a Neural Network

Feature Detection (for Decision Making)

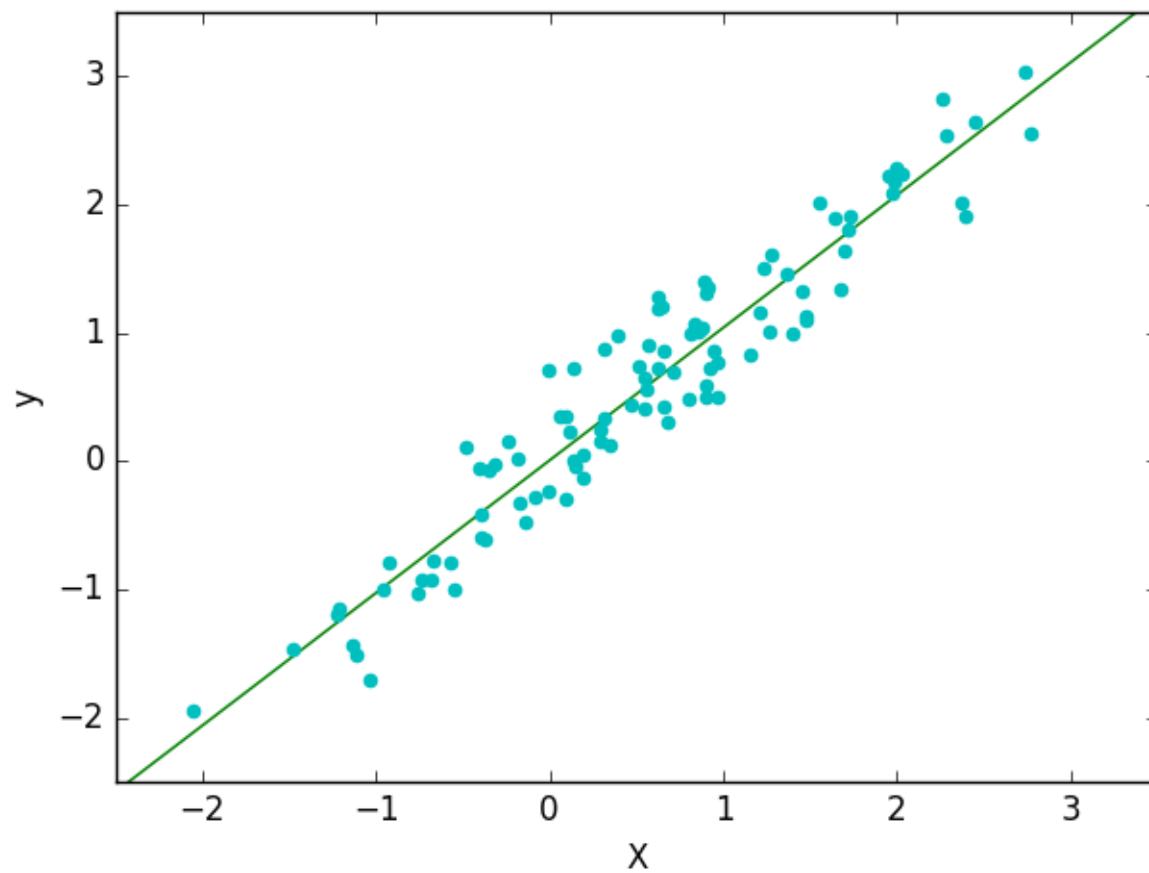
Logistic Regression



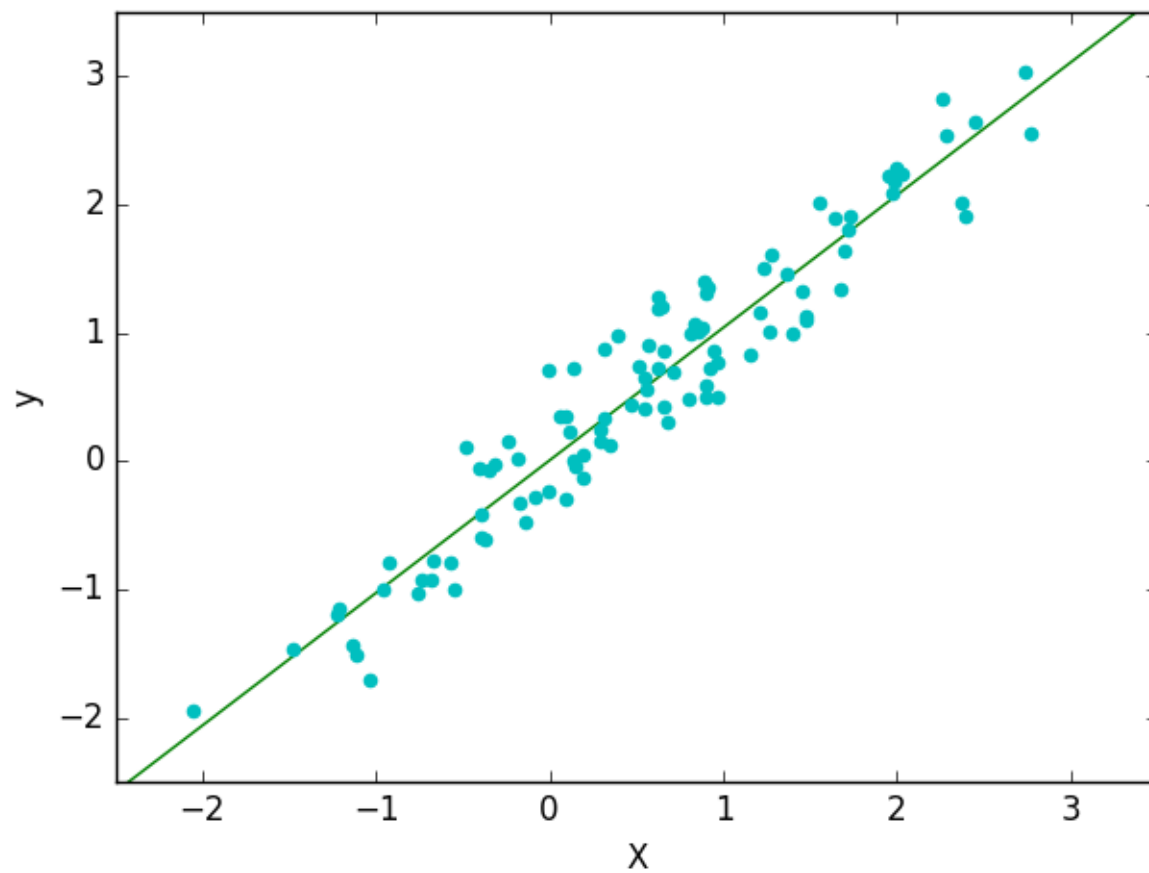
linear
regression



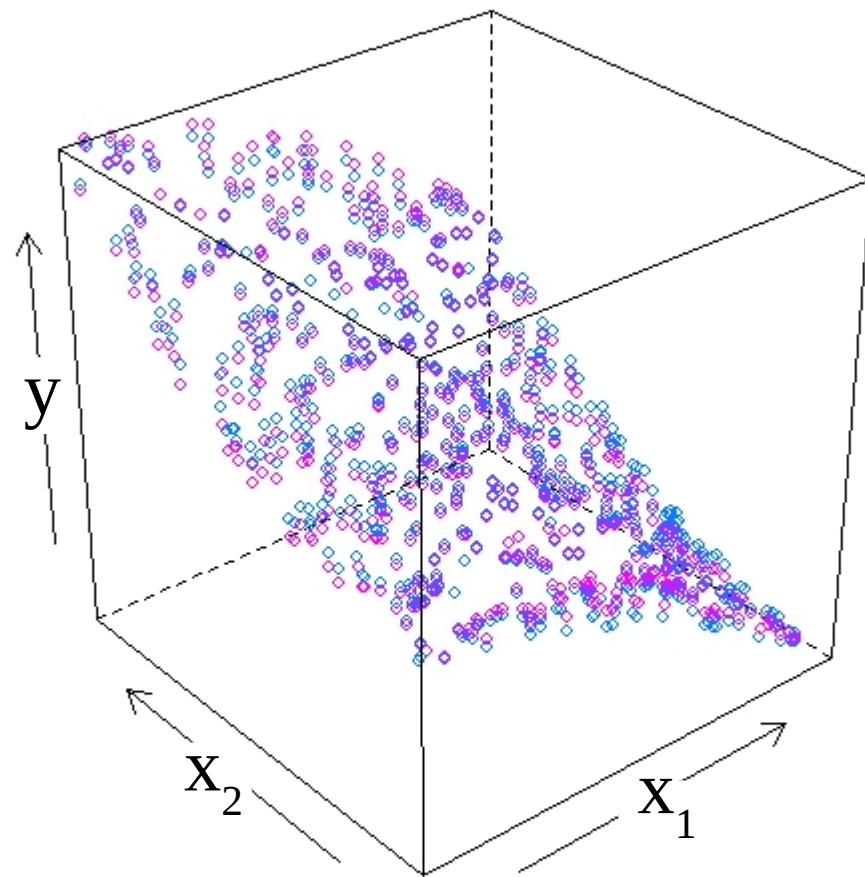
$$y = a * x + b$$



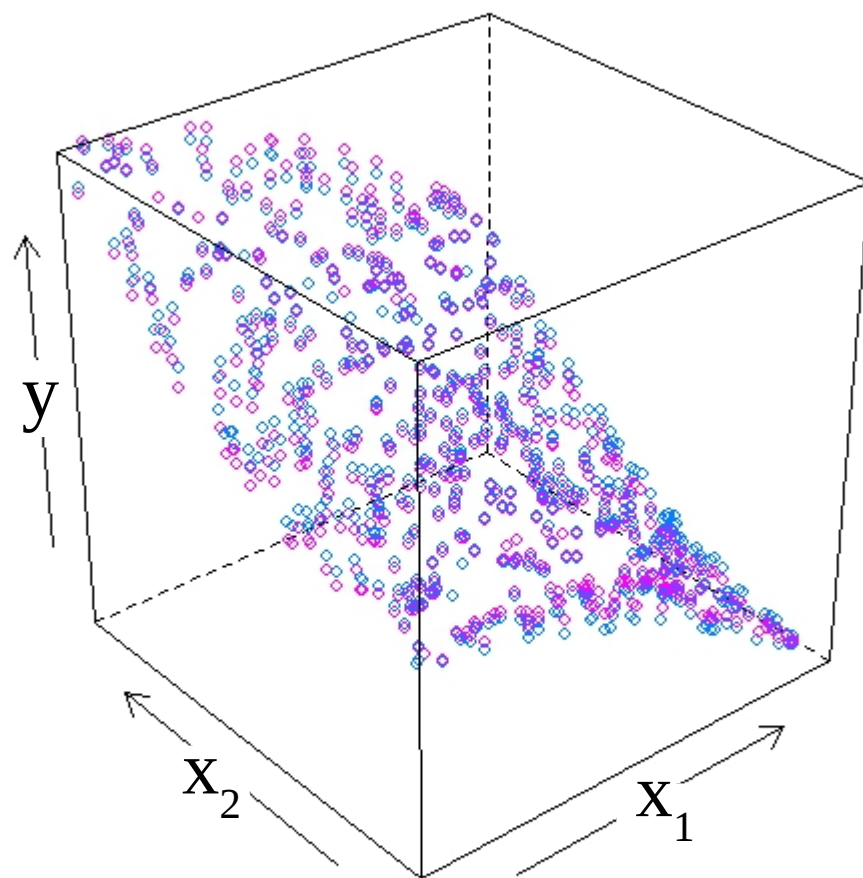
$$y = w * x + b$$

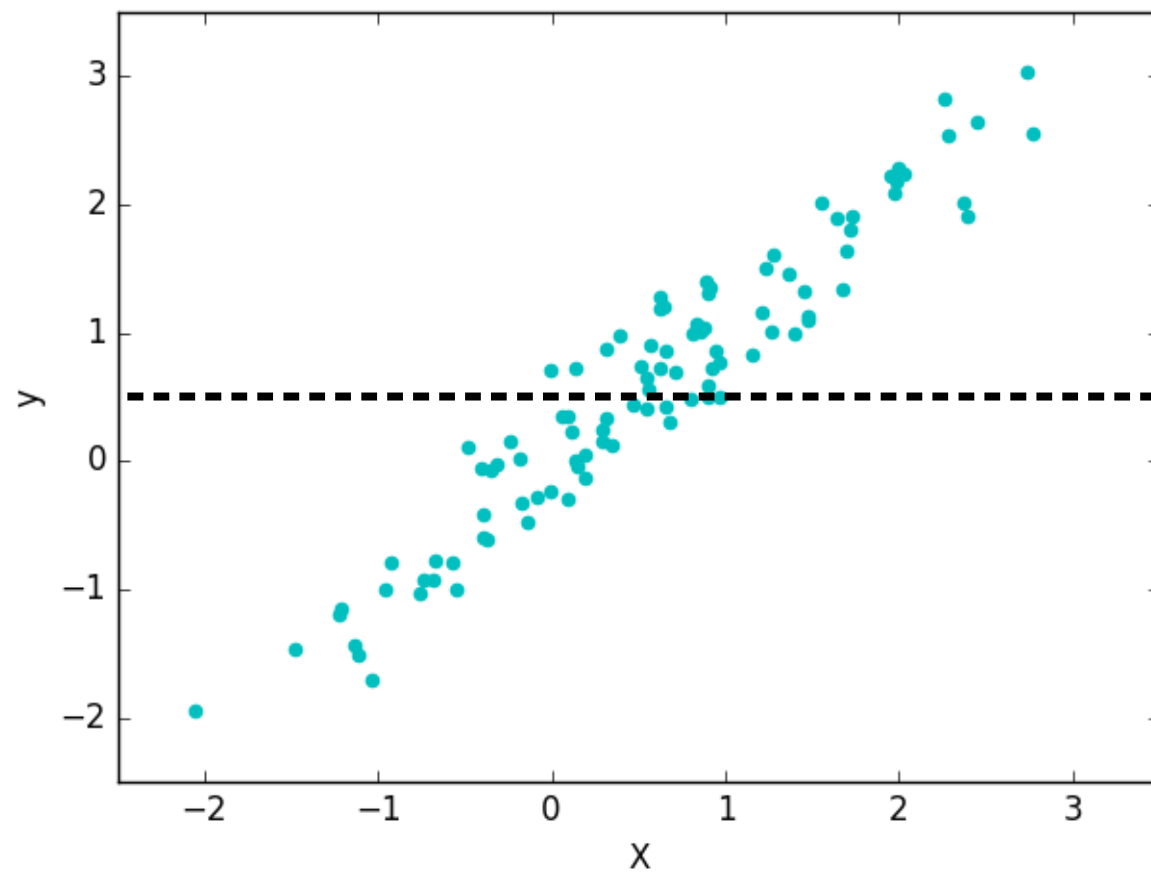


$$y = w_1 * x_1 + w_2 * x_2 + b$$

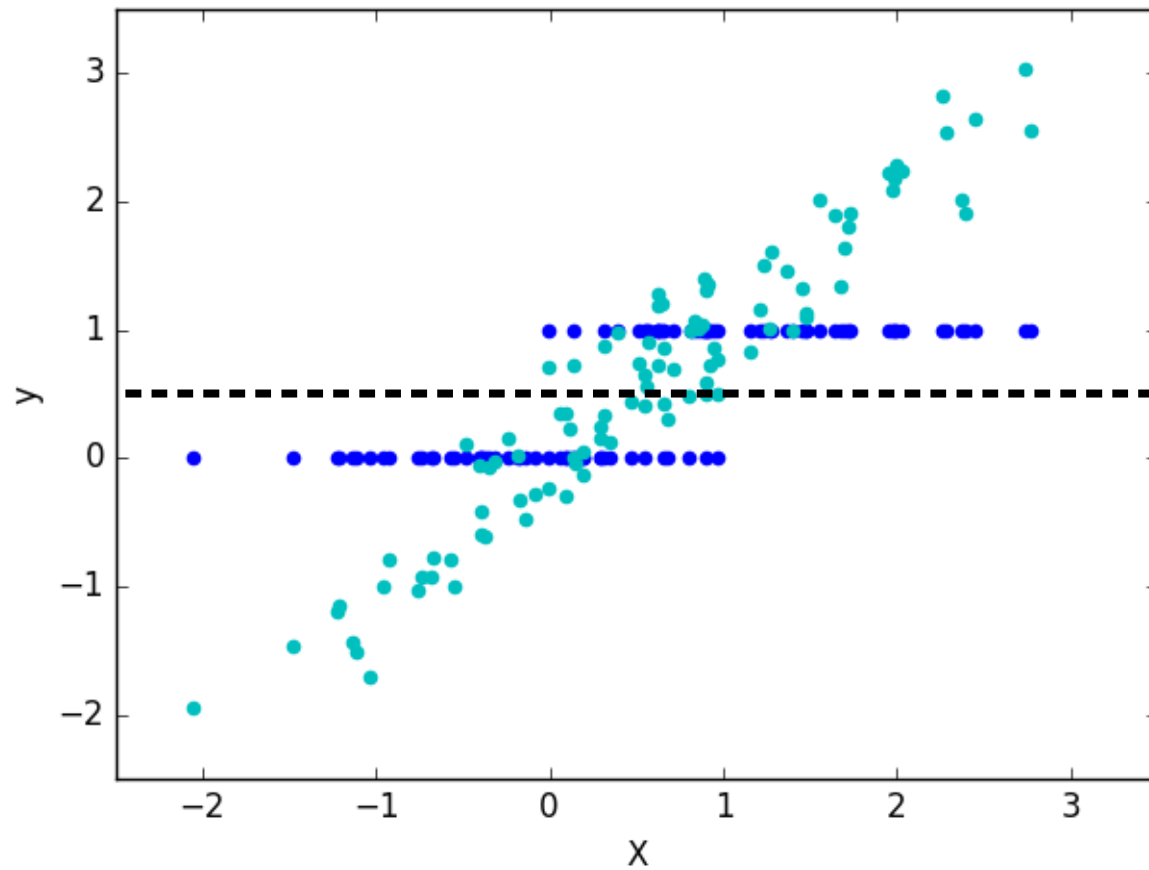


$$y = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} \bullet \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + b$$

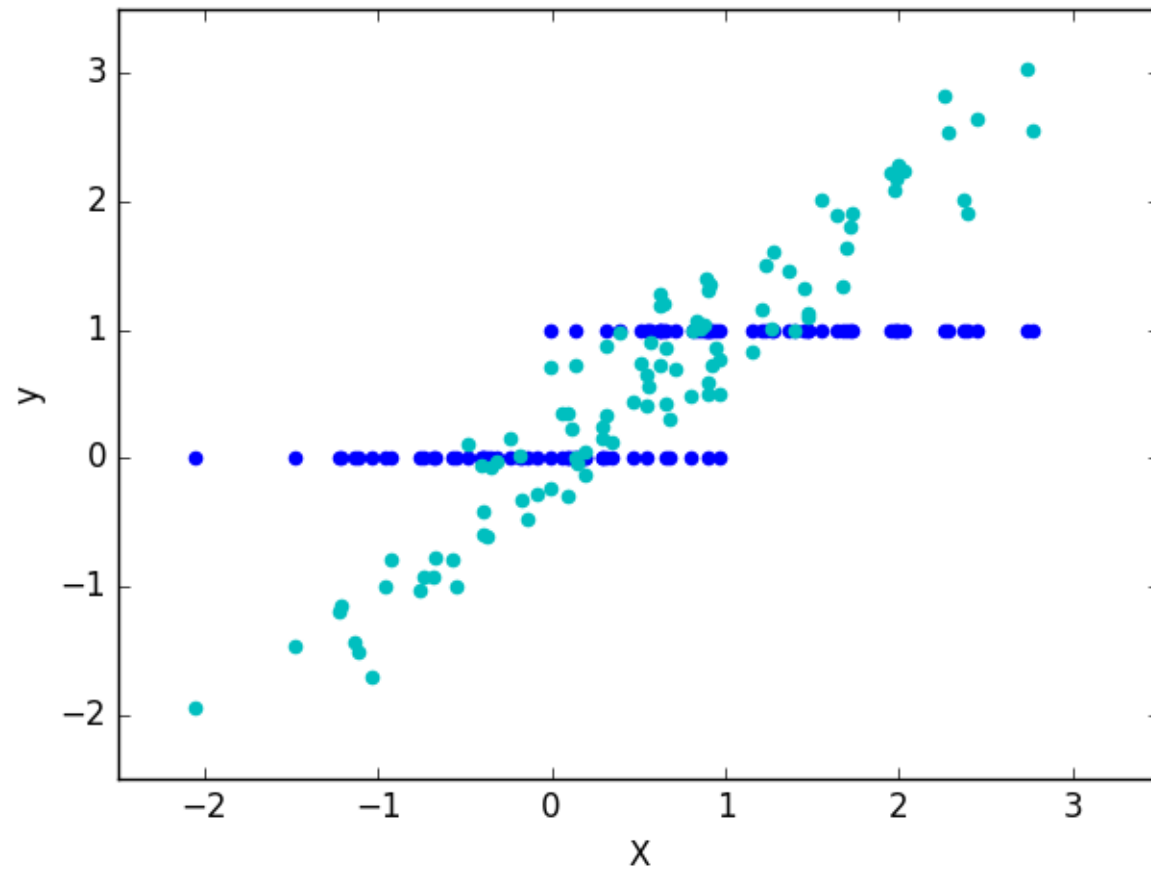




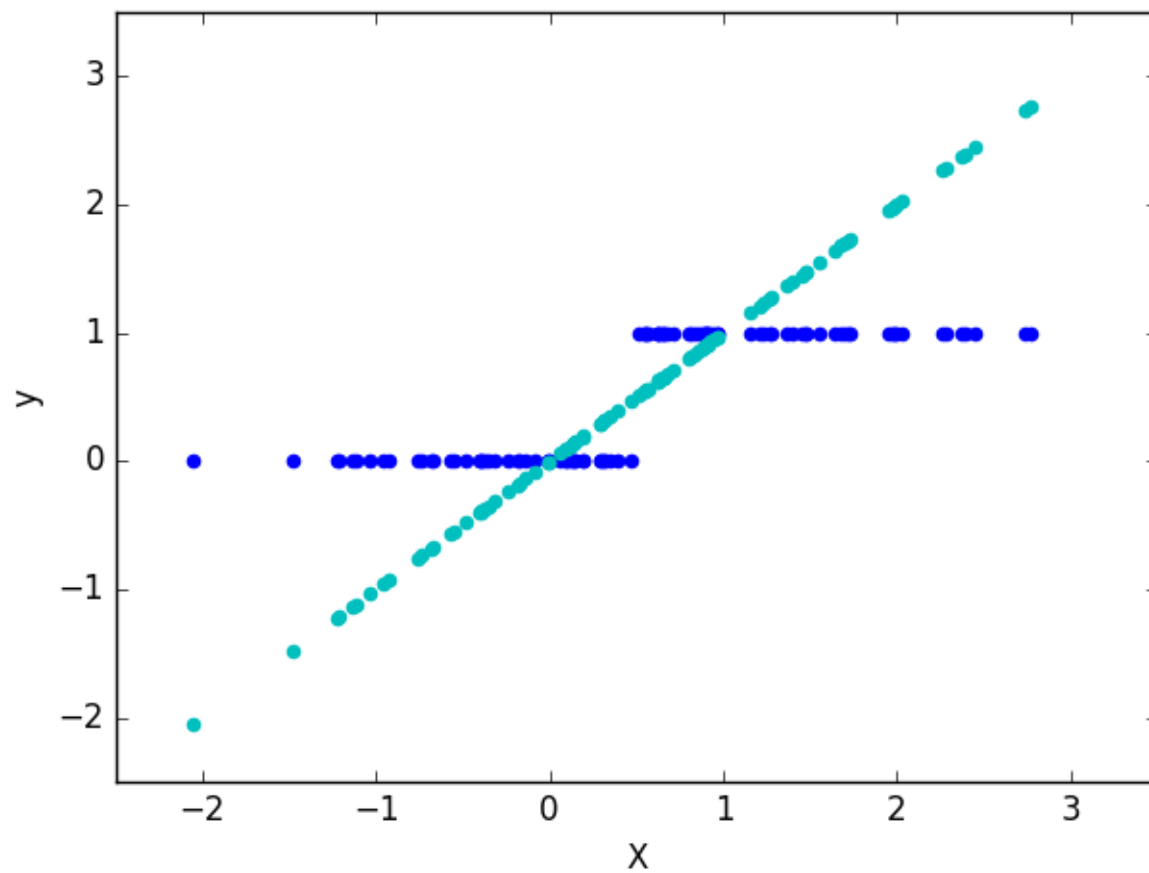
regression $\rightarrow$ classification



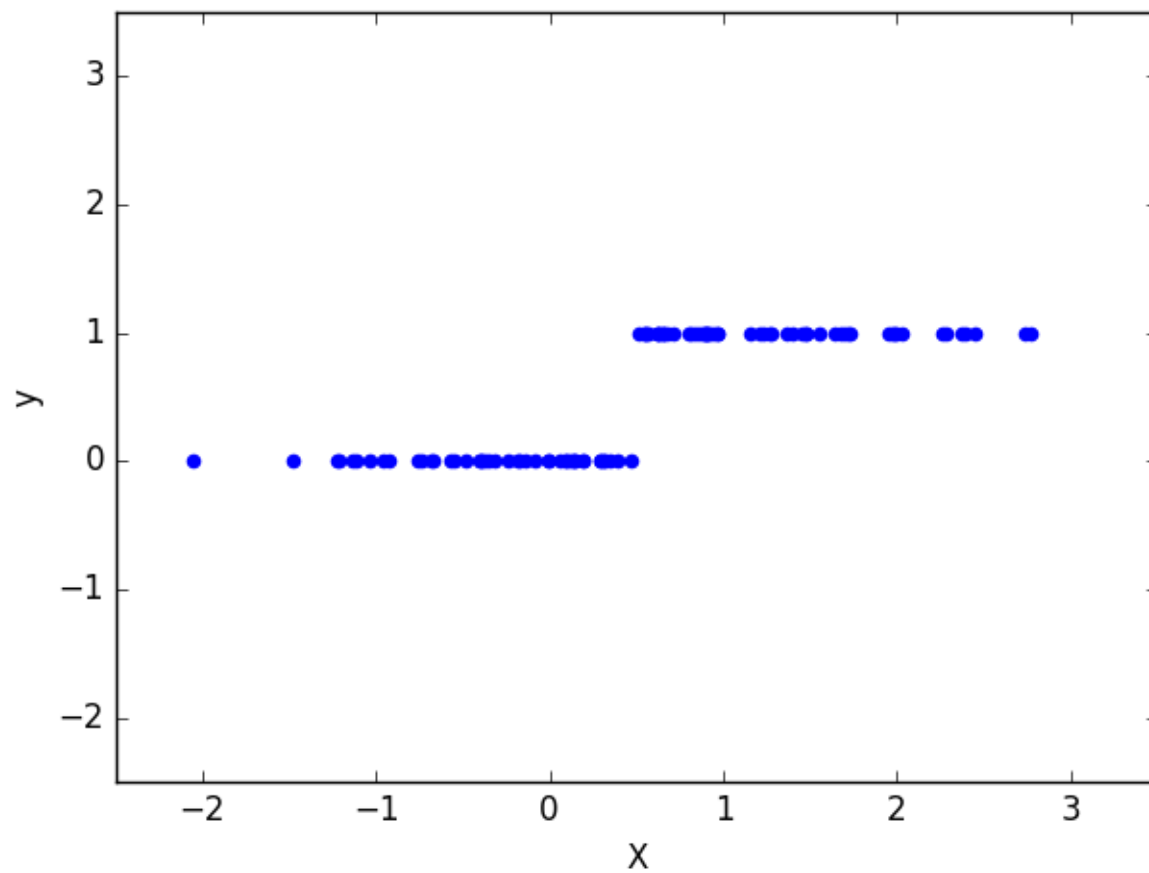
regression $\rightarrow$ classification



(without noise)



(without noise)



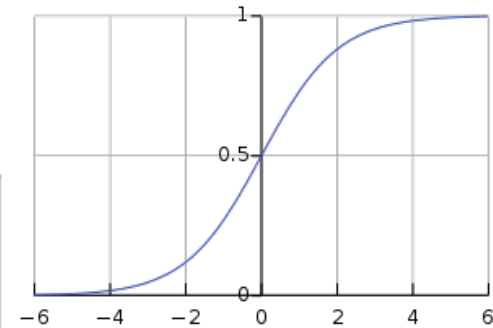
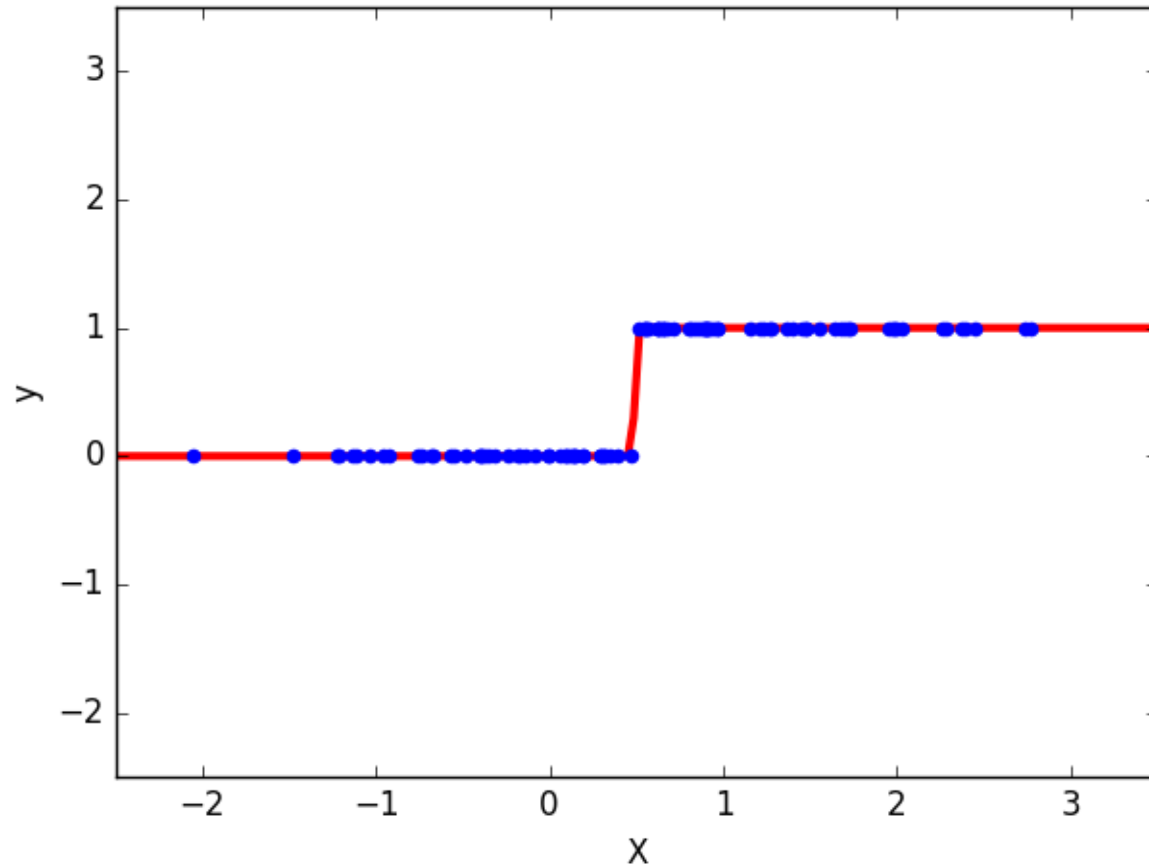
logistic
regression



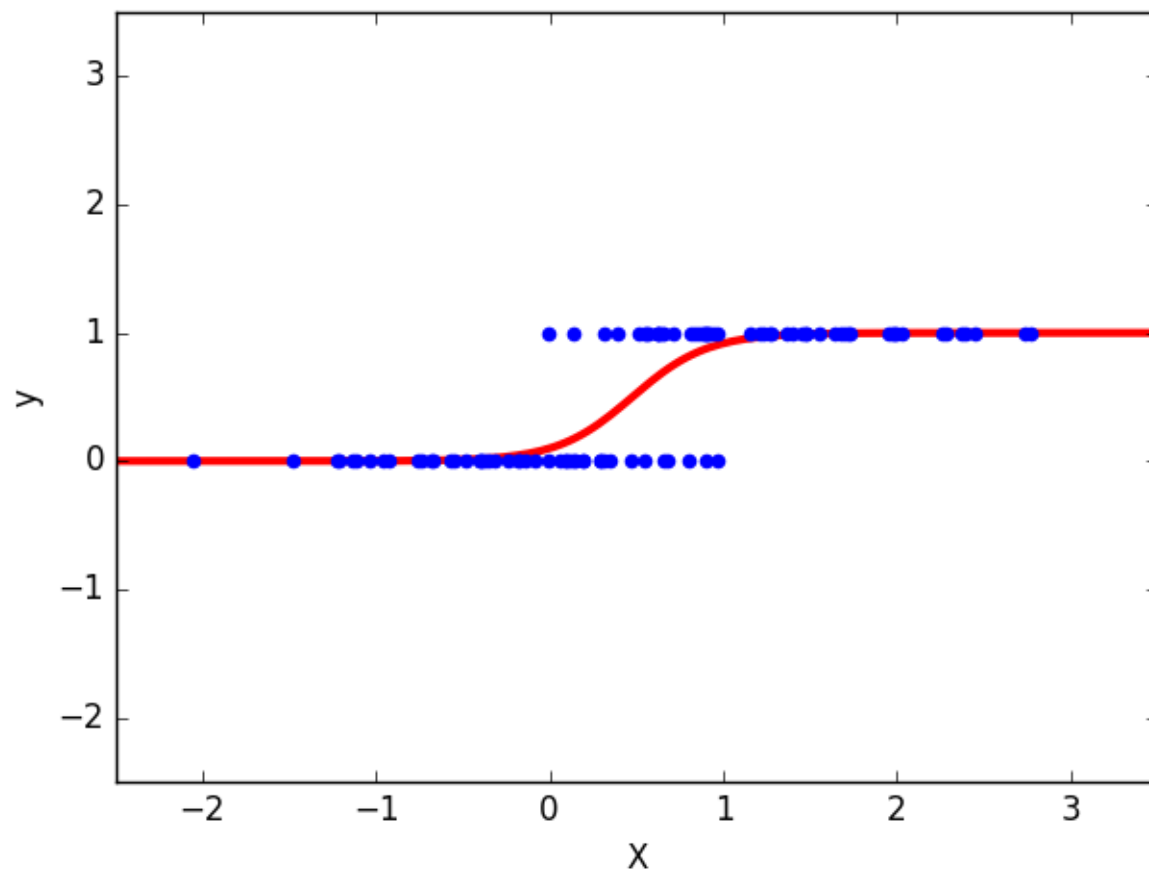
$$y = \sigma(w * x + b)$$

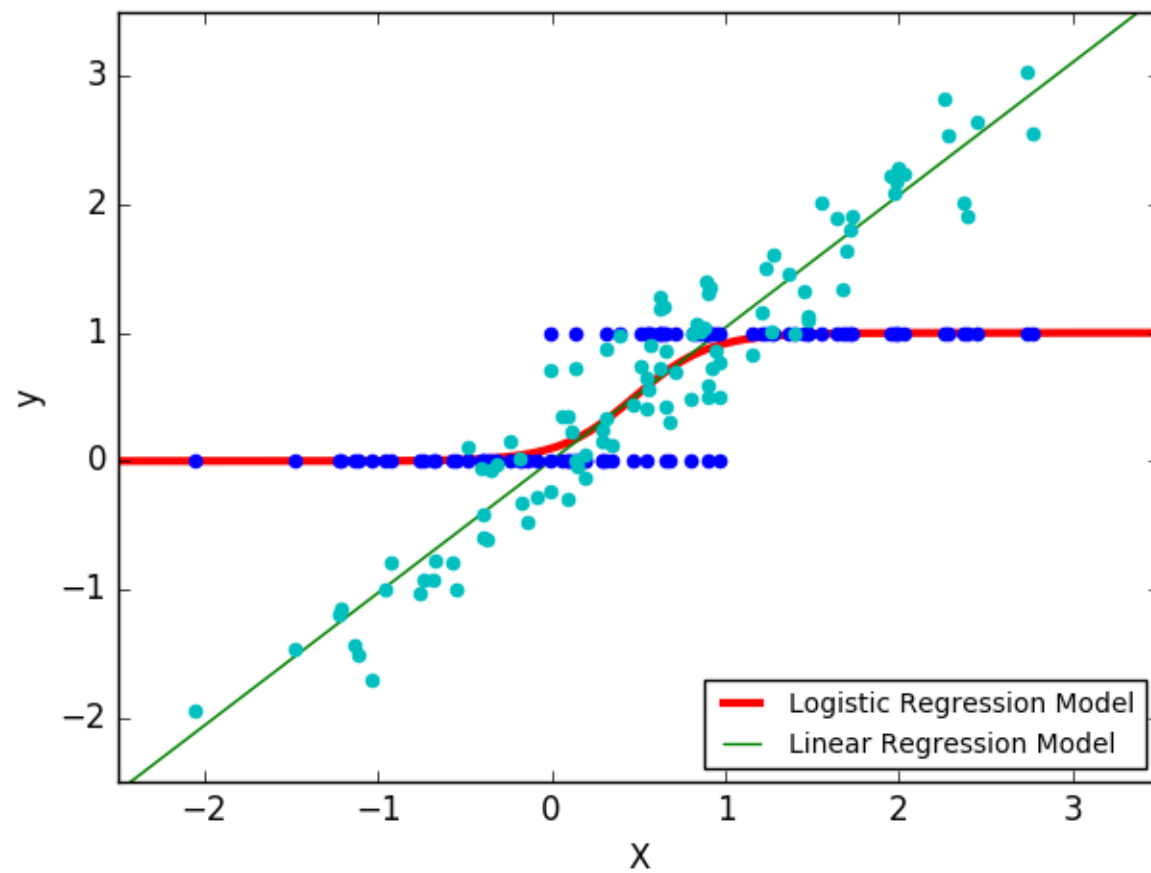


logistic (sigmoid) function

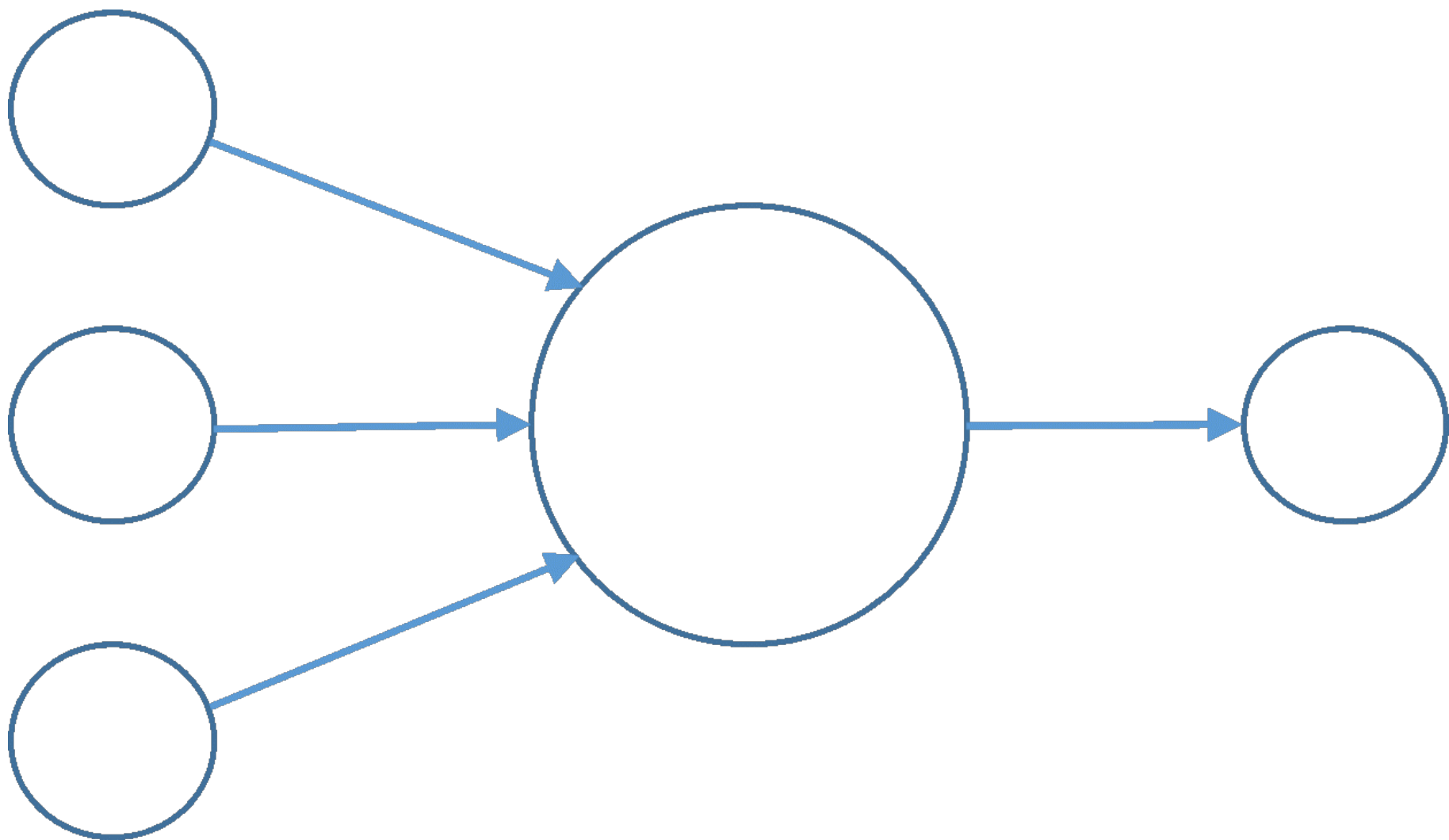


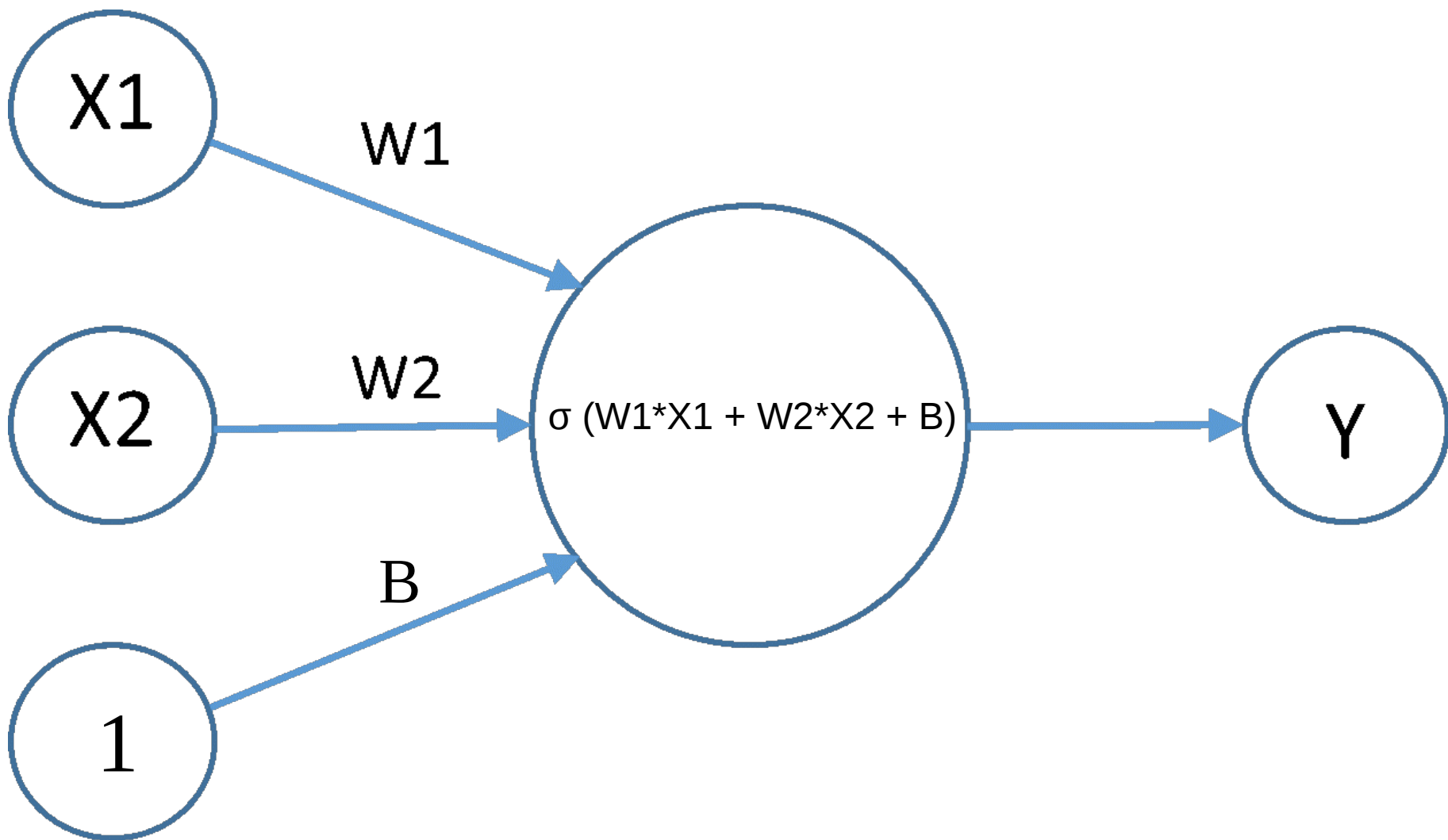
(with the noise)

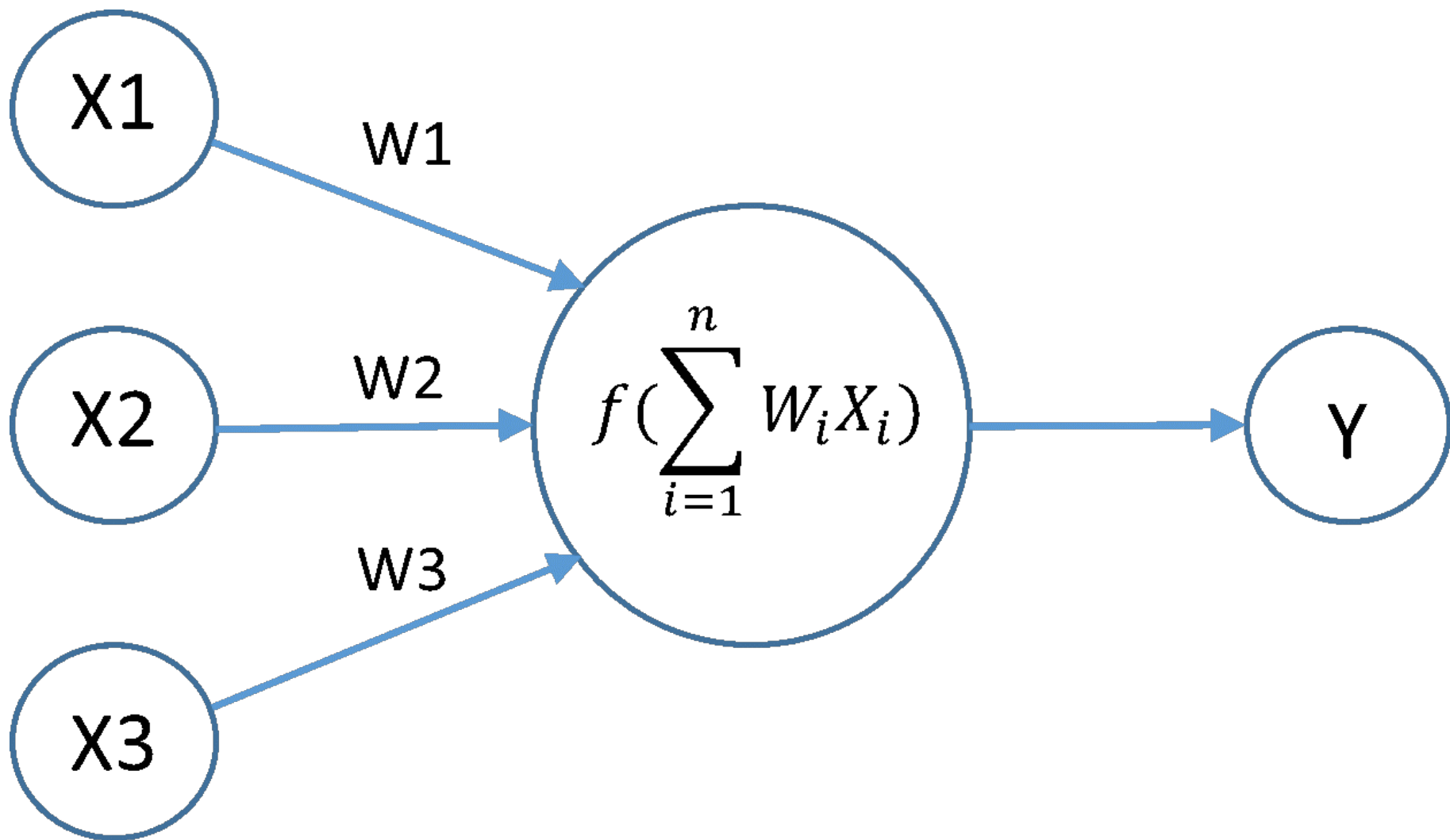




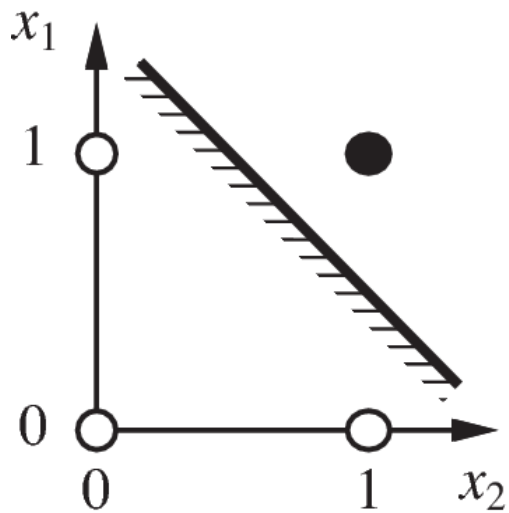
Perceptron



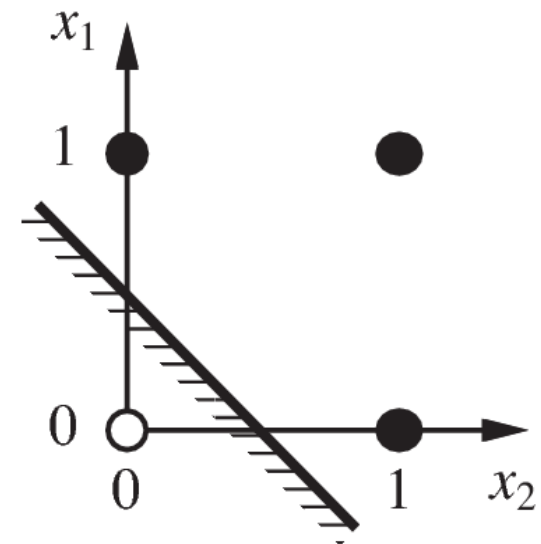




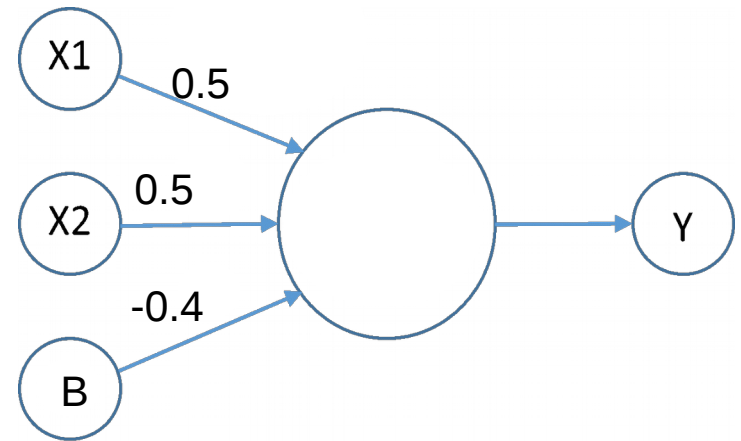
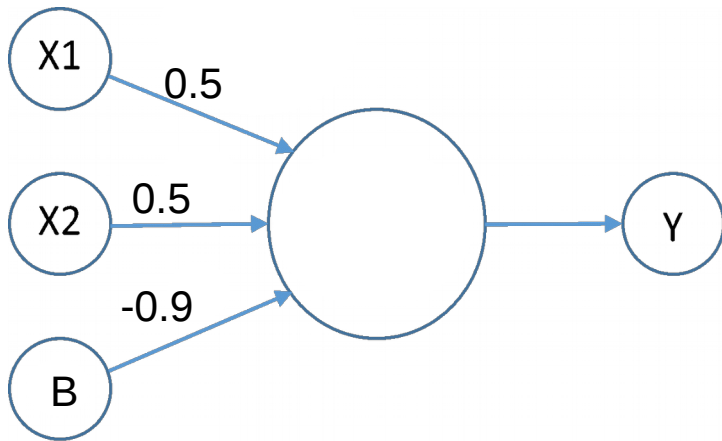
perceptron as logical operator



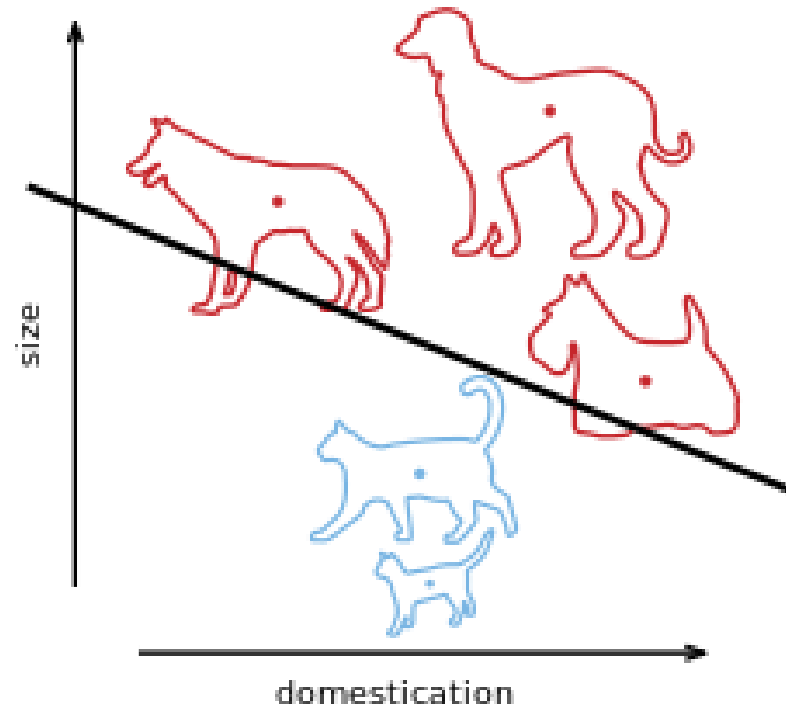
(a) x_1 **and** x_2



(b) x_1 **or** x_2



axes are features of your data



which features should we use???

Multi-Layer Perceptrons

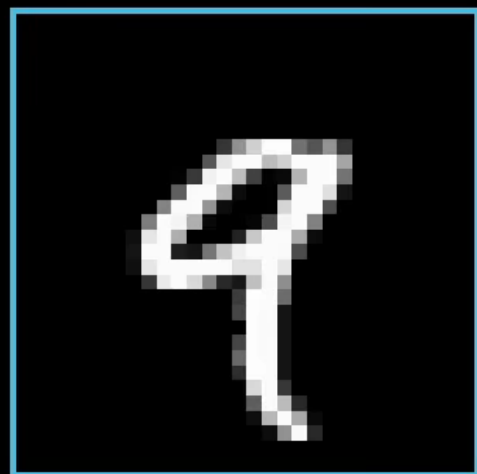
Let's gradually build up abstract features
by applying a classifier to the
outputs of a lower-level classifier!

MNIST

(Modified National Institute of Standards and Technology)

60,000 training images, 10,000 testing images

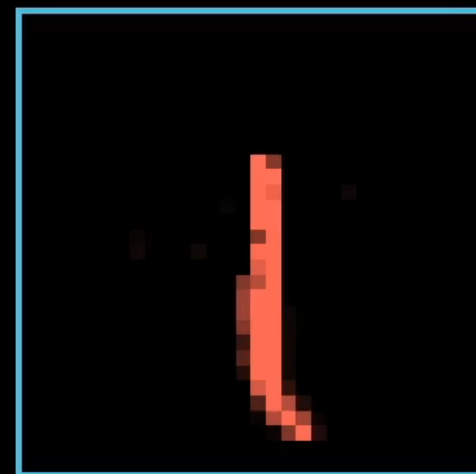


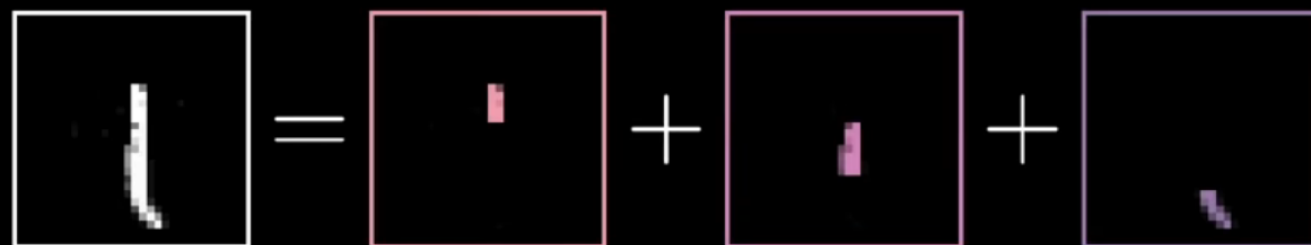
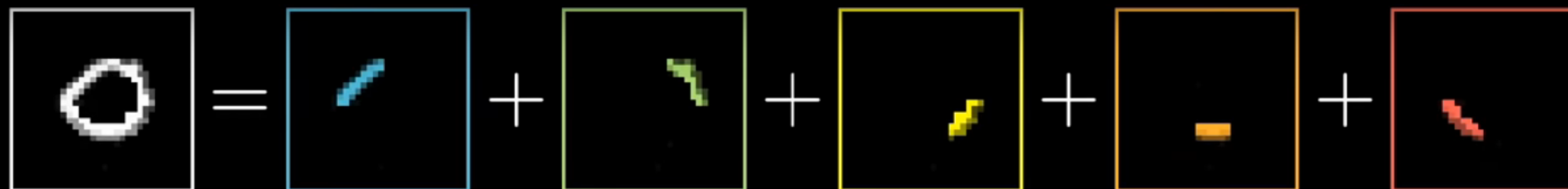
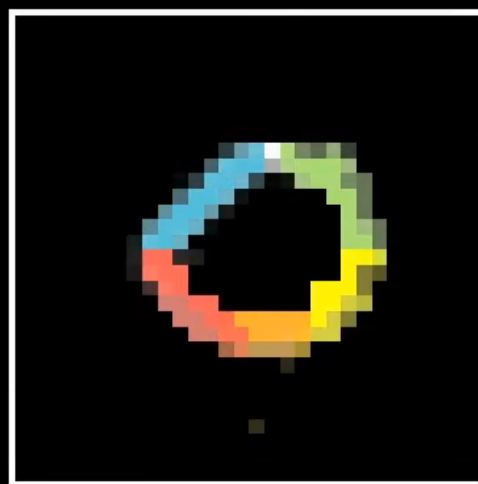


=

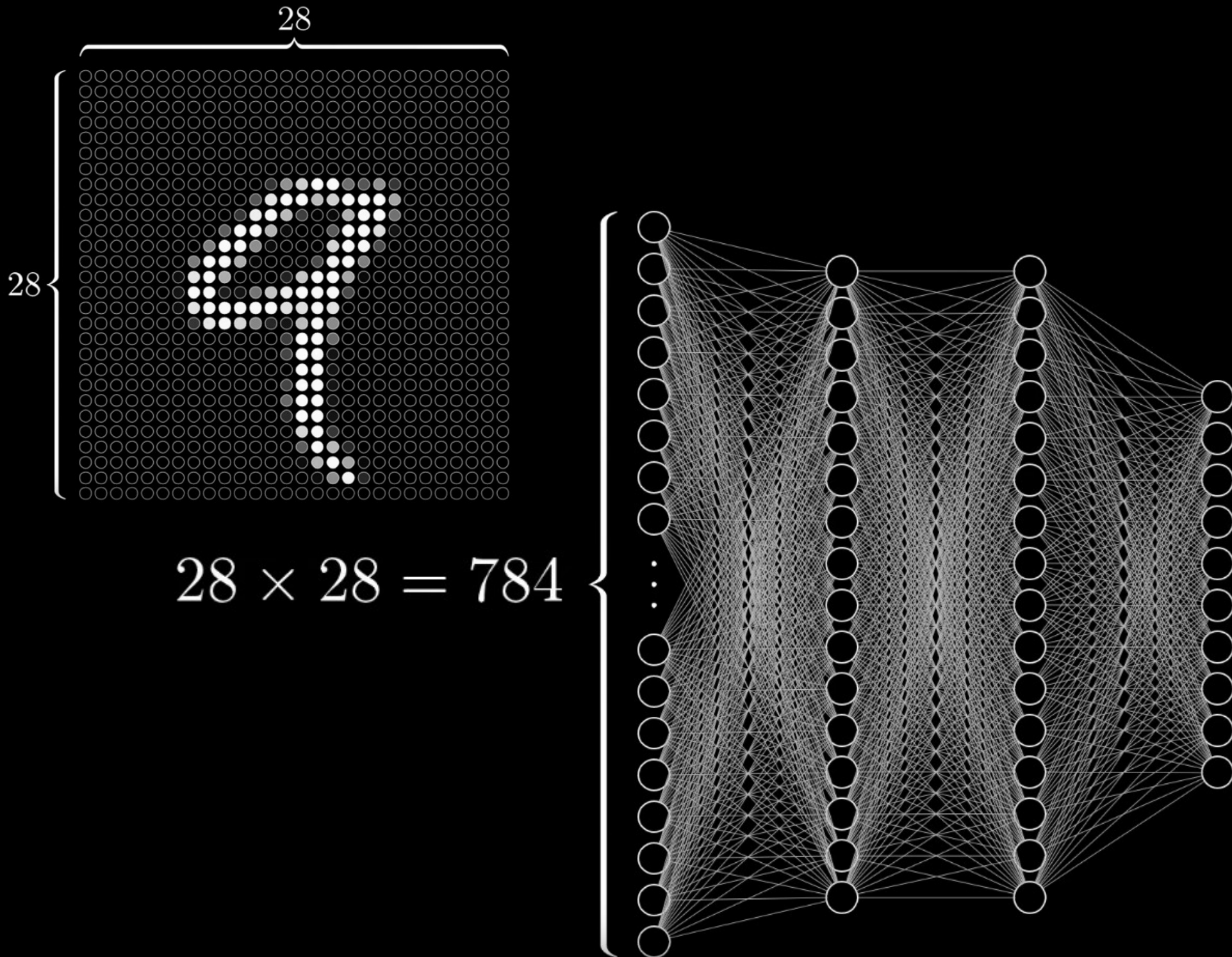


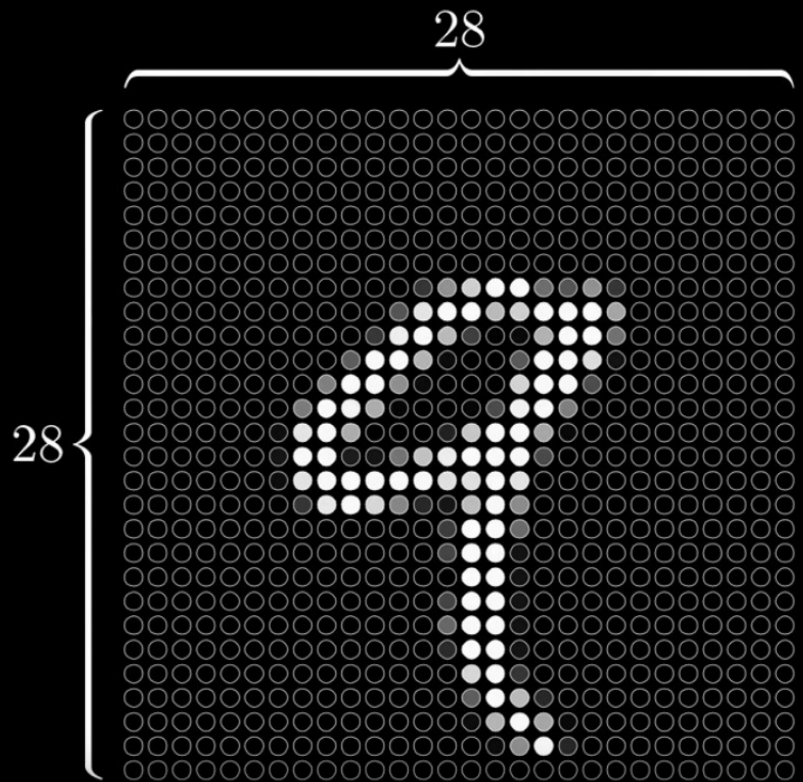
+



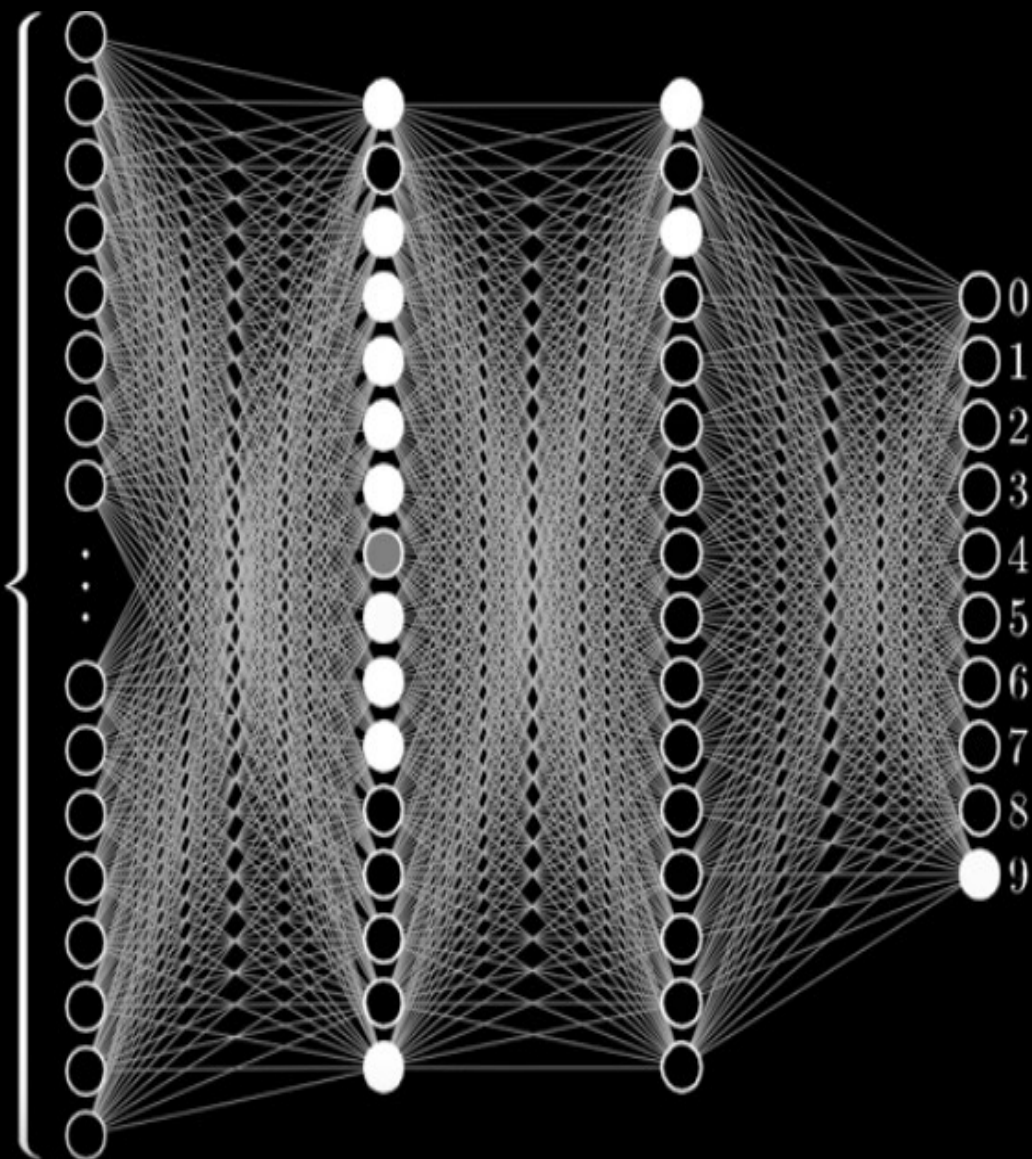


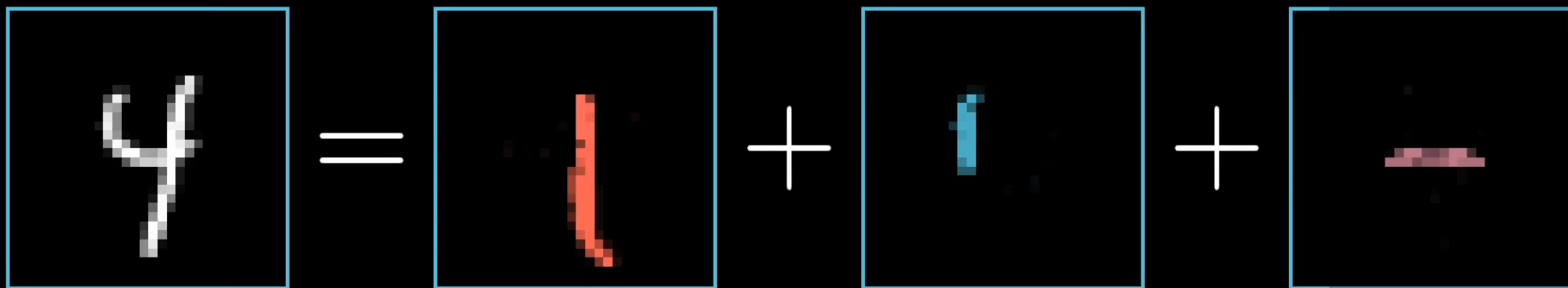


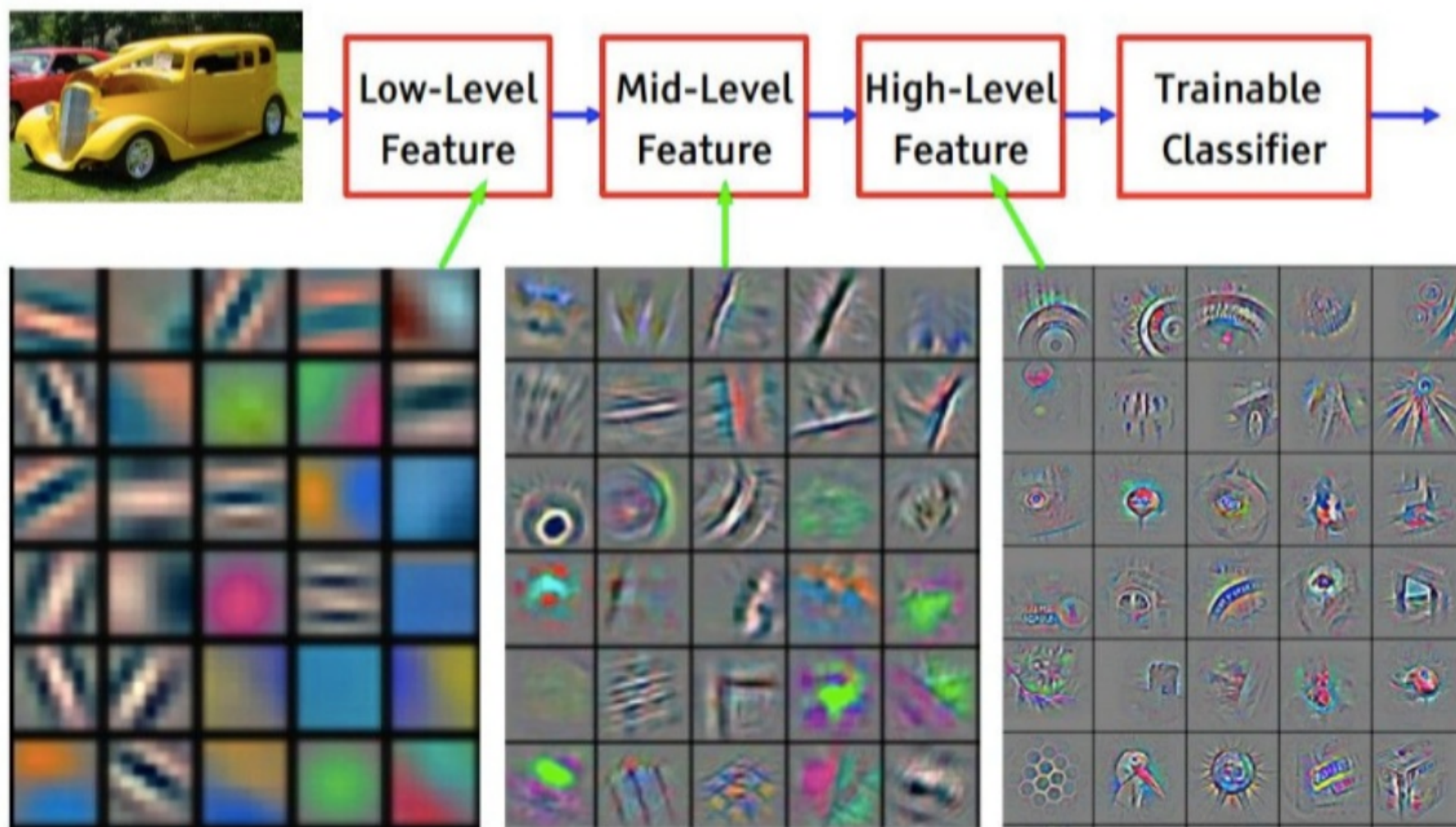




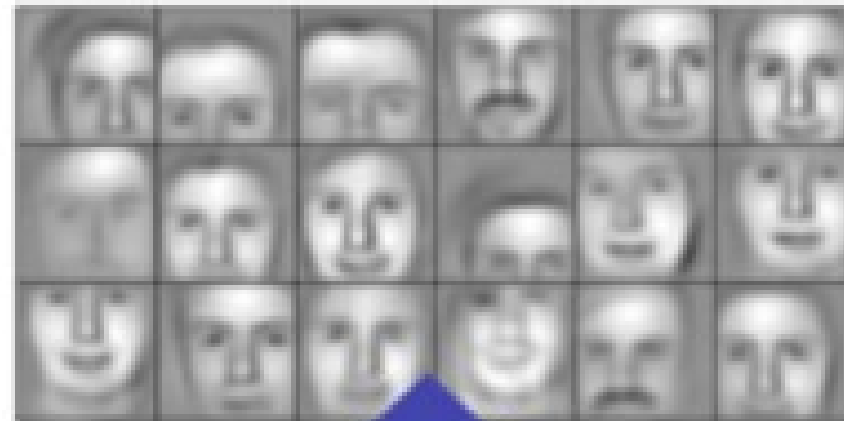
$$28 \times 28 = 784$$



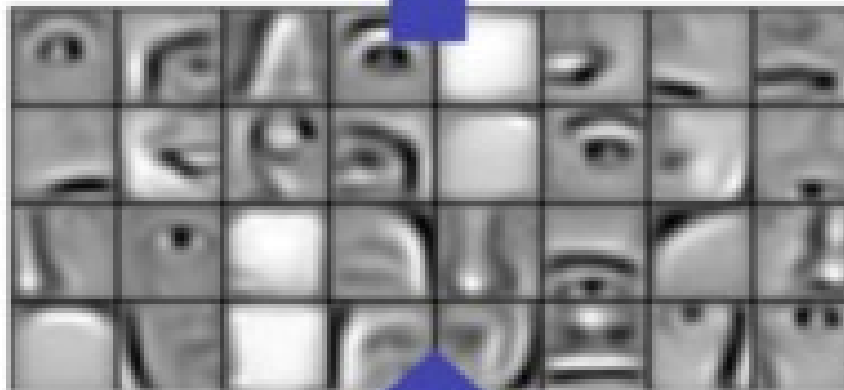




Feature visualization of convolutional net trained on ImageNet from [Zeiler & Fergus 2013]



Layer 3



Layer 2



Layer 1

Supervised Learning

Given (x, y) pairs from the function $y = f(x)$, find f



→ 9



→ lion



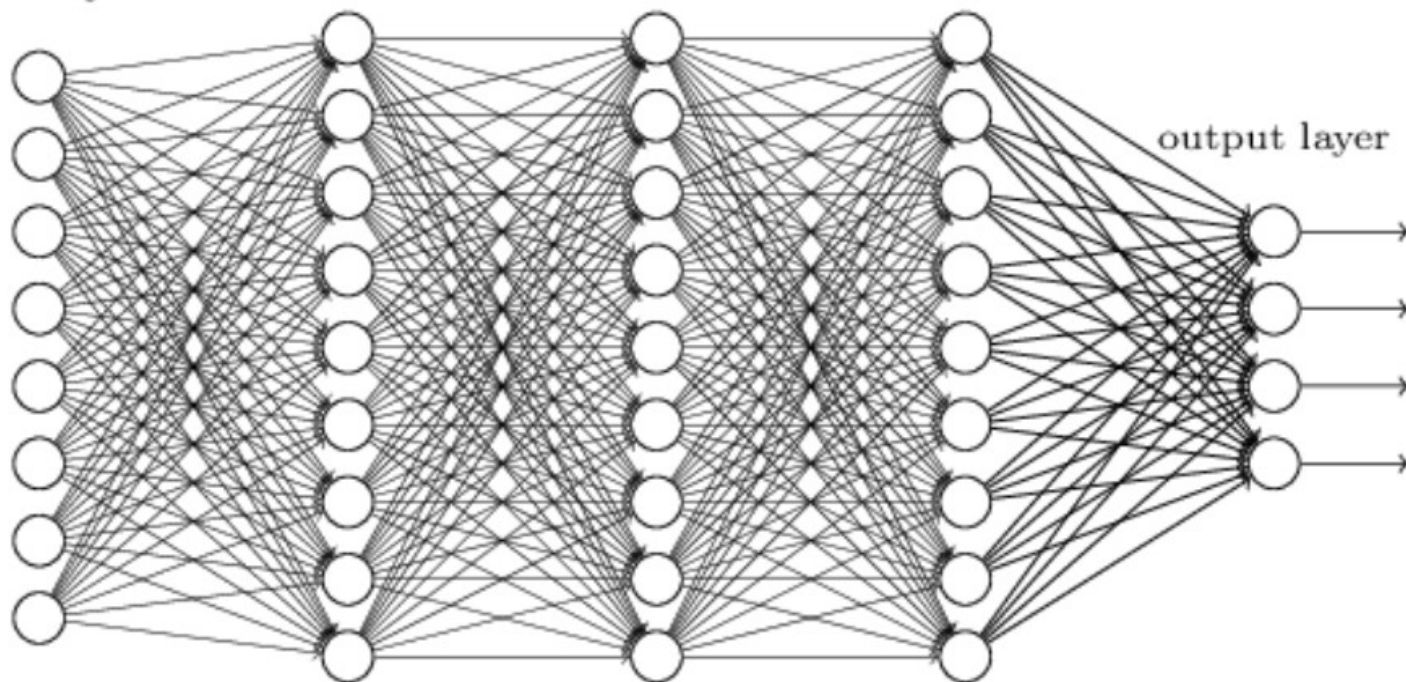
Image

input layer

hidden layer 1

hidden layer 2

hidden layer 3



output layer

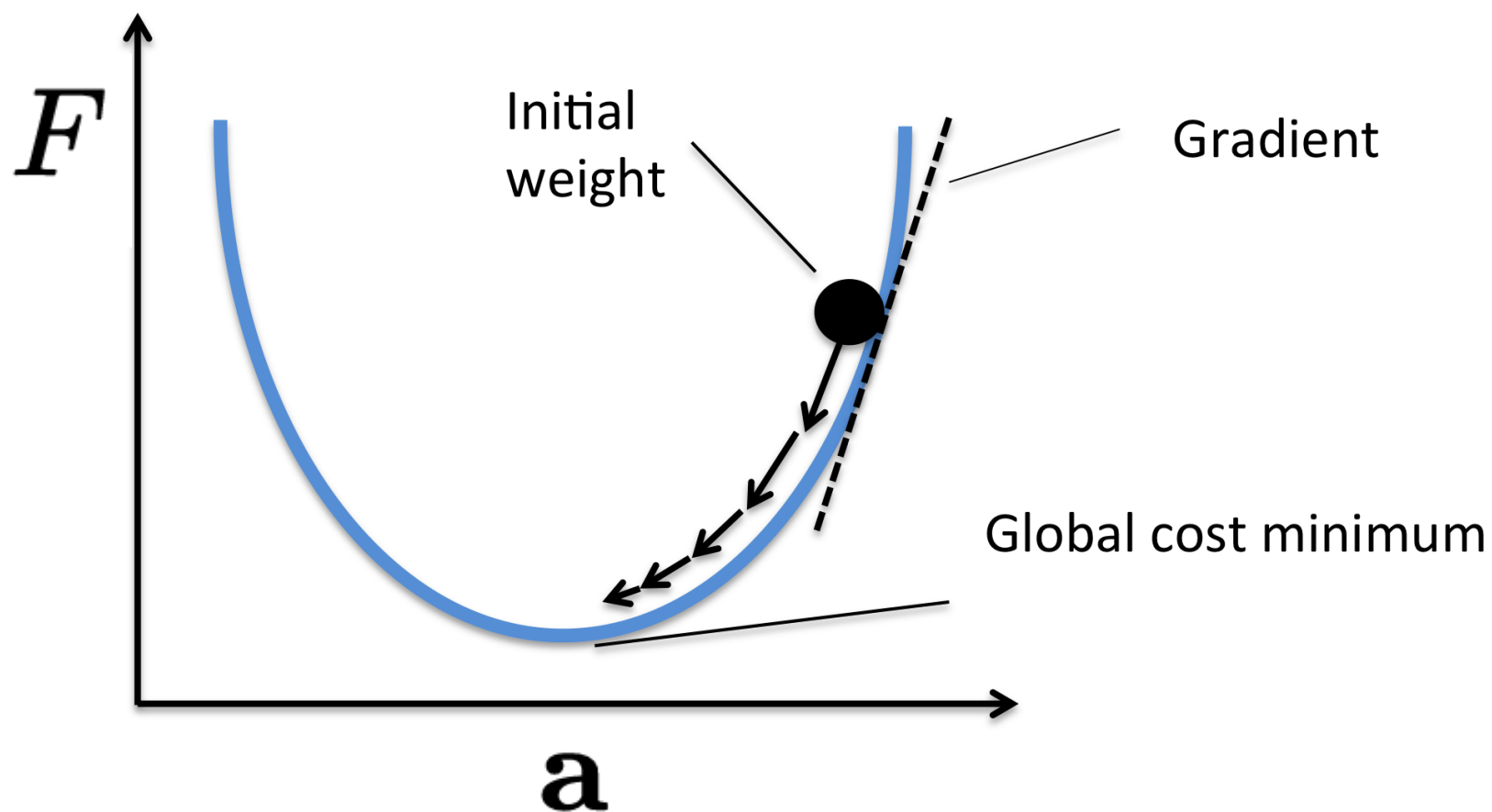
labels

Lion

$$Cost(W) = RSS(W) = \sum_{i=1}^N \{y_i - \hat{y}_i\}^2$$

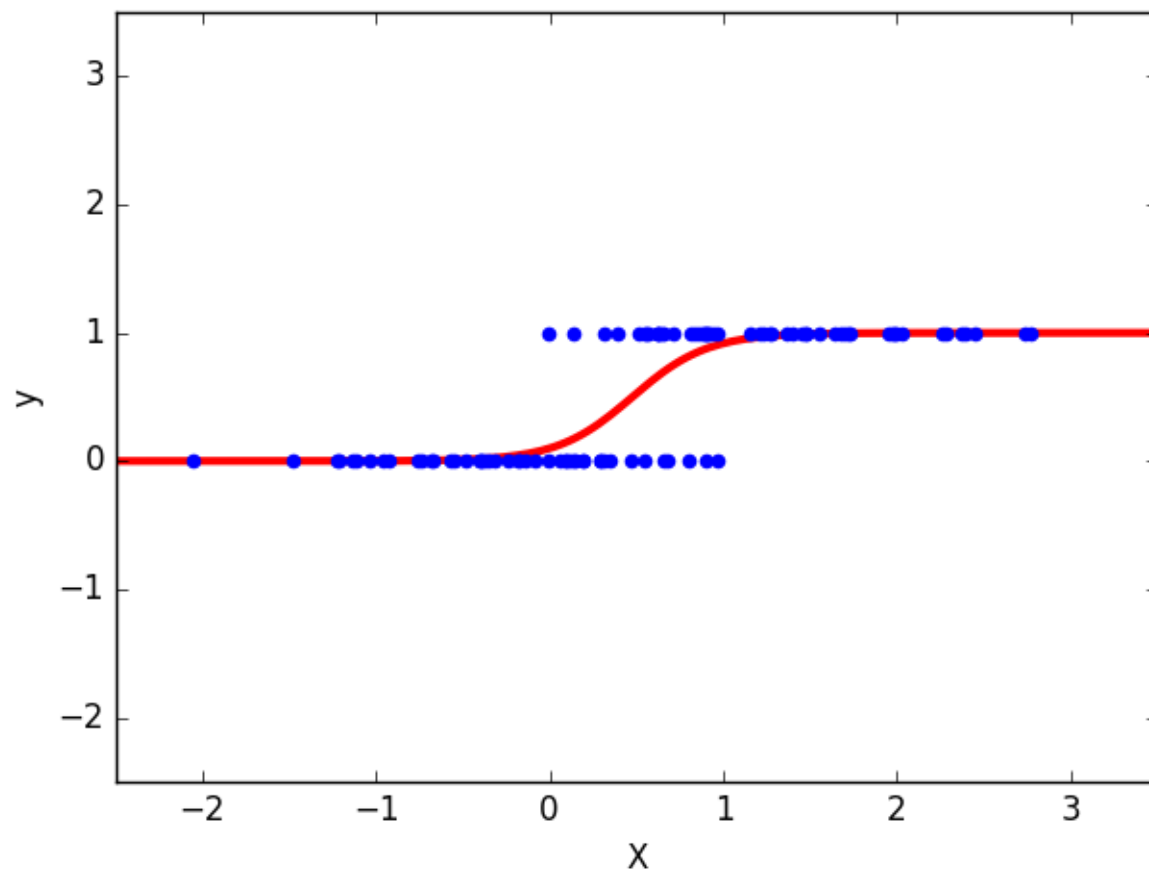
Gradient Descent

$$\mathbf{a}_{n+1} = \mathbf{a}_n - \gamma \nabla F(\mathbf{a}_n)$$

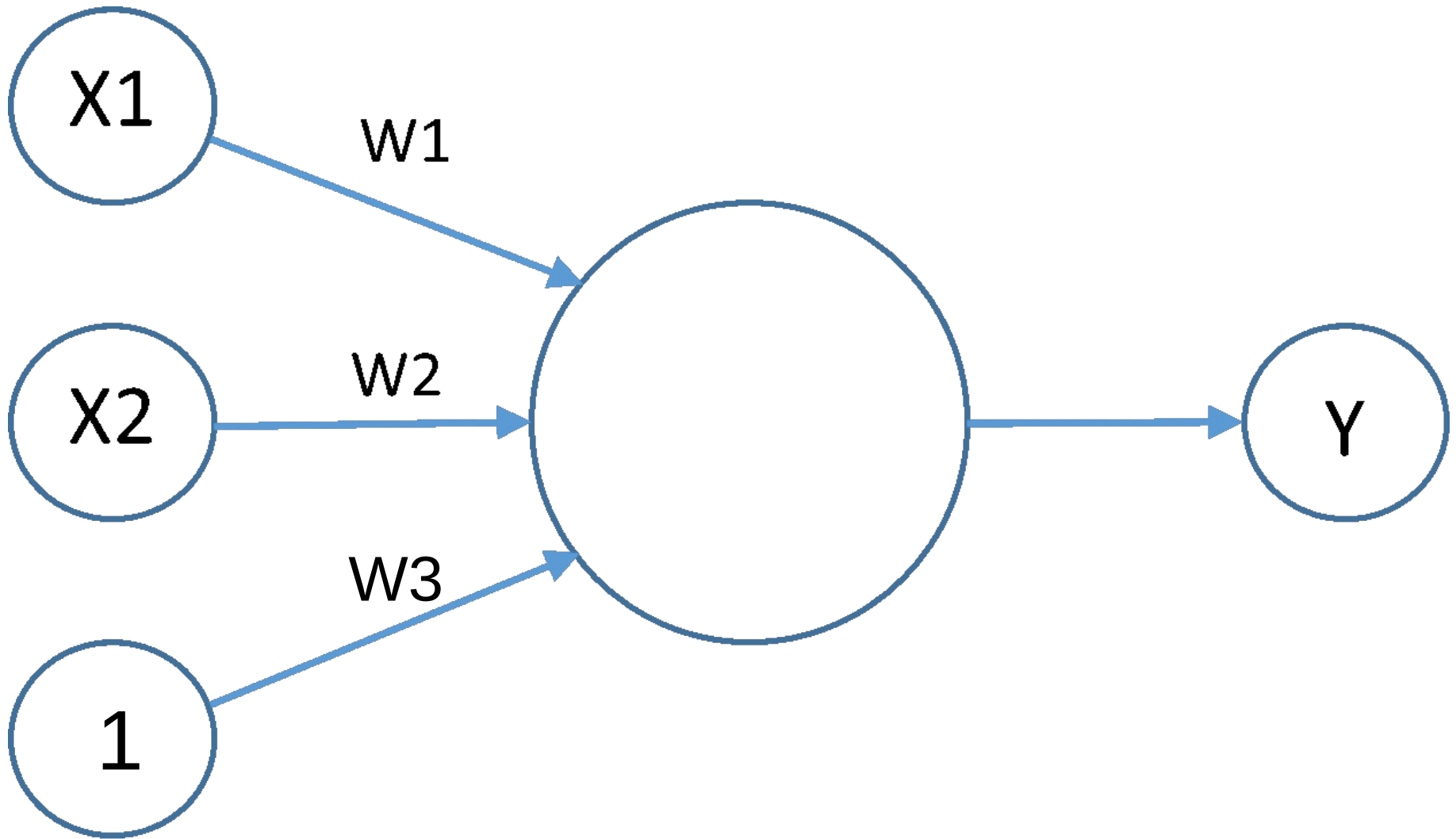


Backpropagation

$$y = \sigma(w * x + b)$$



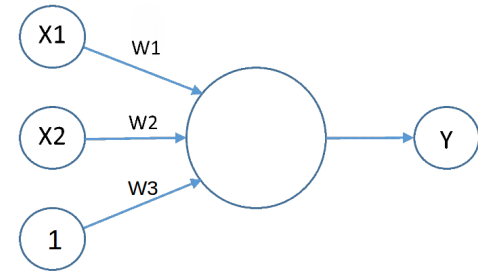
$$y = \sigma(w_1 * x_1 + w_2 * x_2 + w_3 * 1)$$



$$y = \sigma(w_1 * x_1 + w_2 * x_2 + w_3 * 1)$$

$$y = \sigma(z)$$

$$z = w_1 * x_1 + w_2 * x_2 + w_3 * 1$$



$$\frac{\partial y}{\partial w_1} = \frac{\partial y}{\partial z} * \frac{\partial z}{\partial w_1}$$

$$\frac{\partial y}{\partial z} = \sigma(z) * (1 - \sigma(z))$$

$$\frac{\partial z}{\partial w_1} = x_1$$

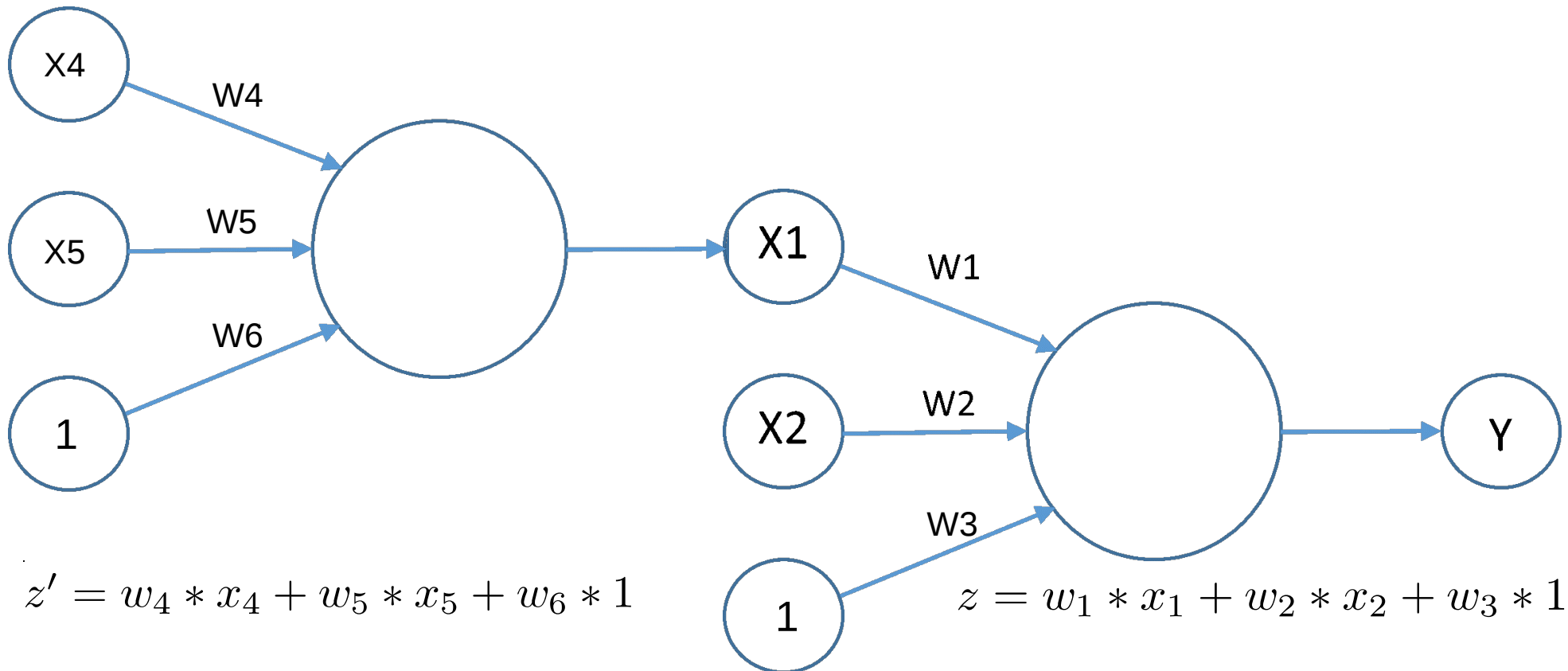
$$\frac{\partial y}{\partial w_1} = \frac{\partial y}{\partial z} * \frac{\partial z}{\partial w_1} = \sigma(z) * (1 - \sigma(z)) * x_1$$

$$\frac{\partial y}{\partial w_2} = \sigma(z) * (1 - \sigma(z)) * x_2$$

$$\frac{\partial y}{\partial w_4} = \frac{\partial y}{\partial x_1} * \frac{\partial x_1}{\partial w_4}$$

$$\frac{\partial y}{\partial x_1} = \sigma(z) * (1 - \sigma(z)) * w_1$$

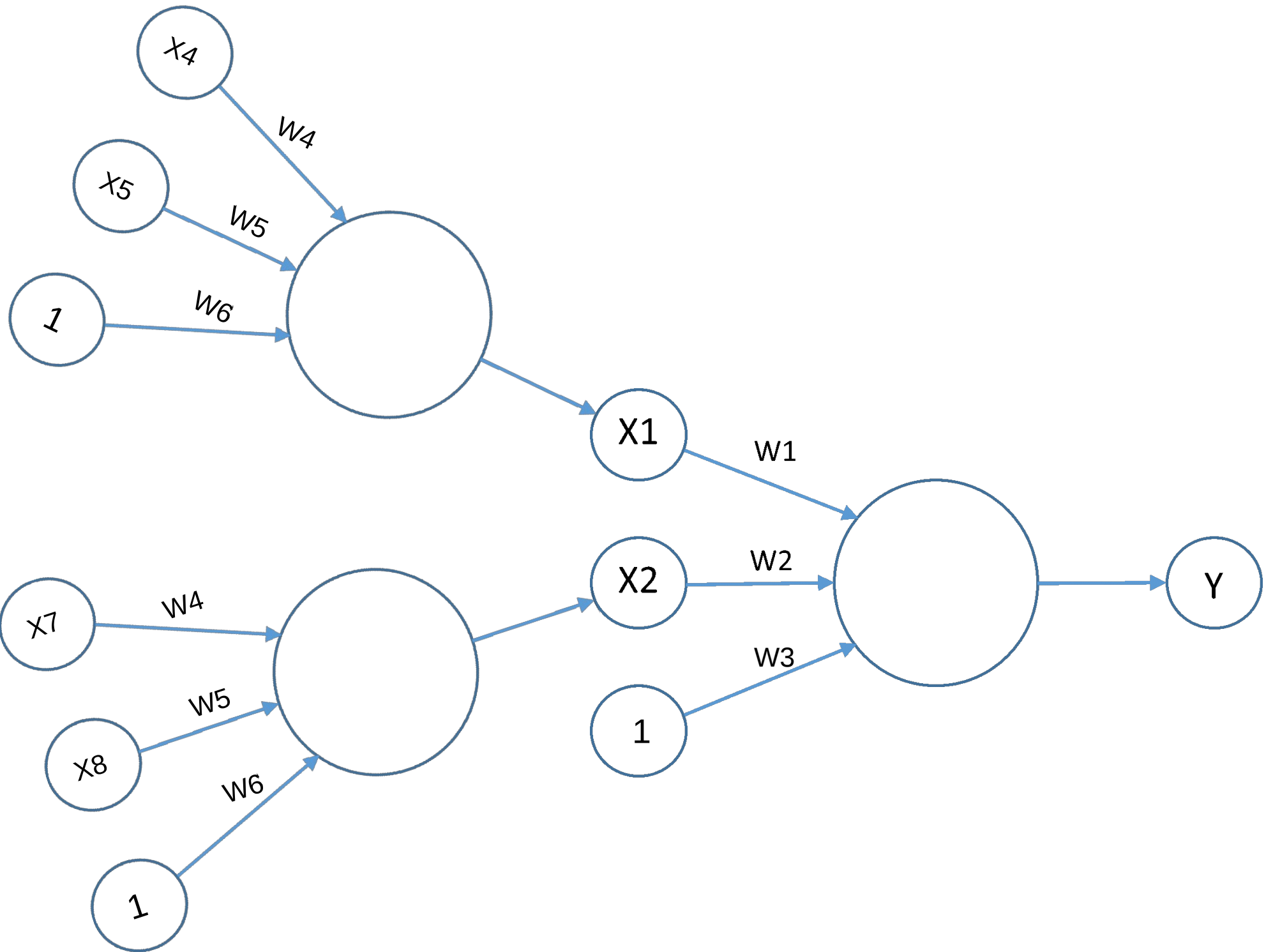
$$\frac{\partial x_1}{\partial w_4} = \sigma(z') * (1 - \sigma(z')) * x_4$$

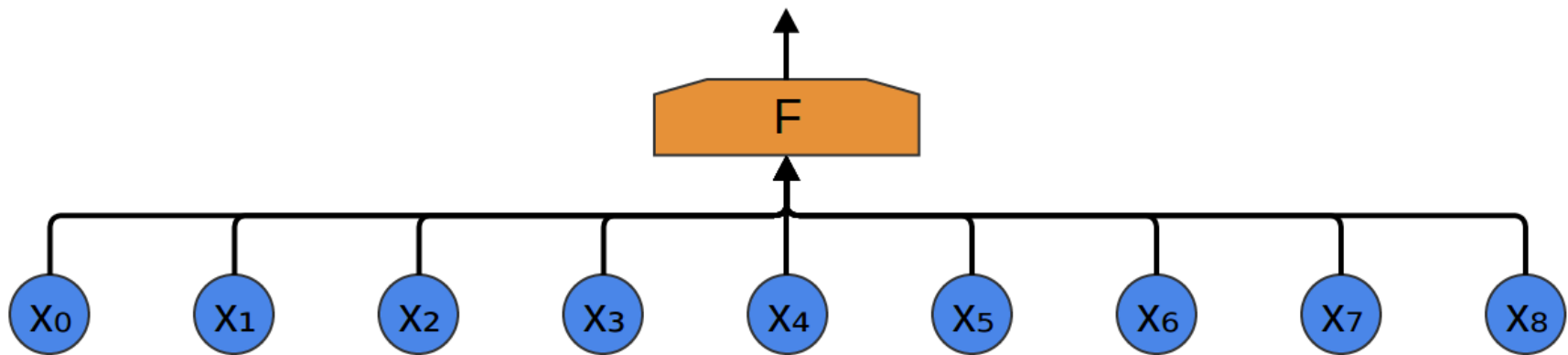


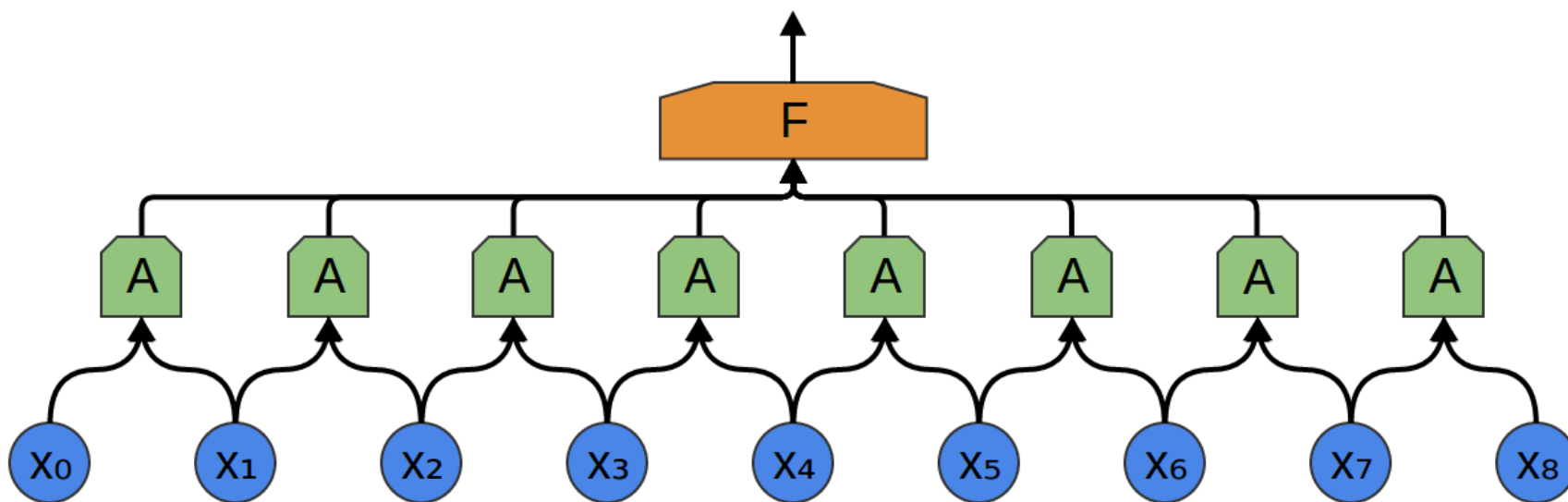
**Tricks that make
this work/scale!**

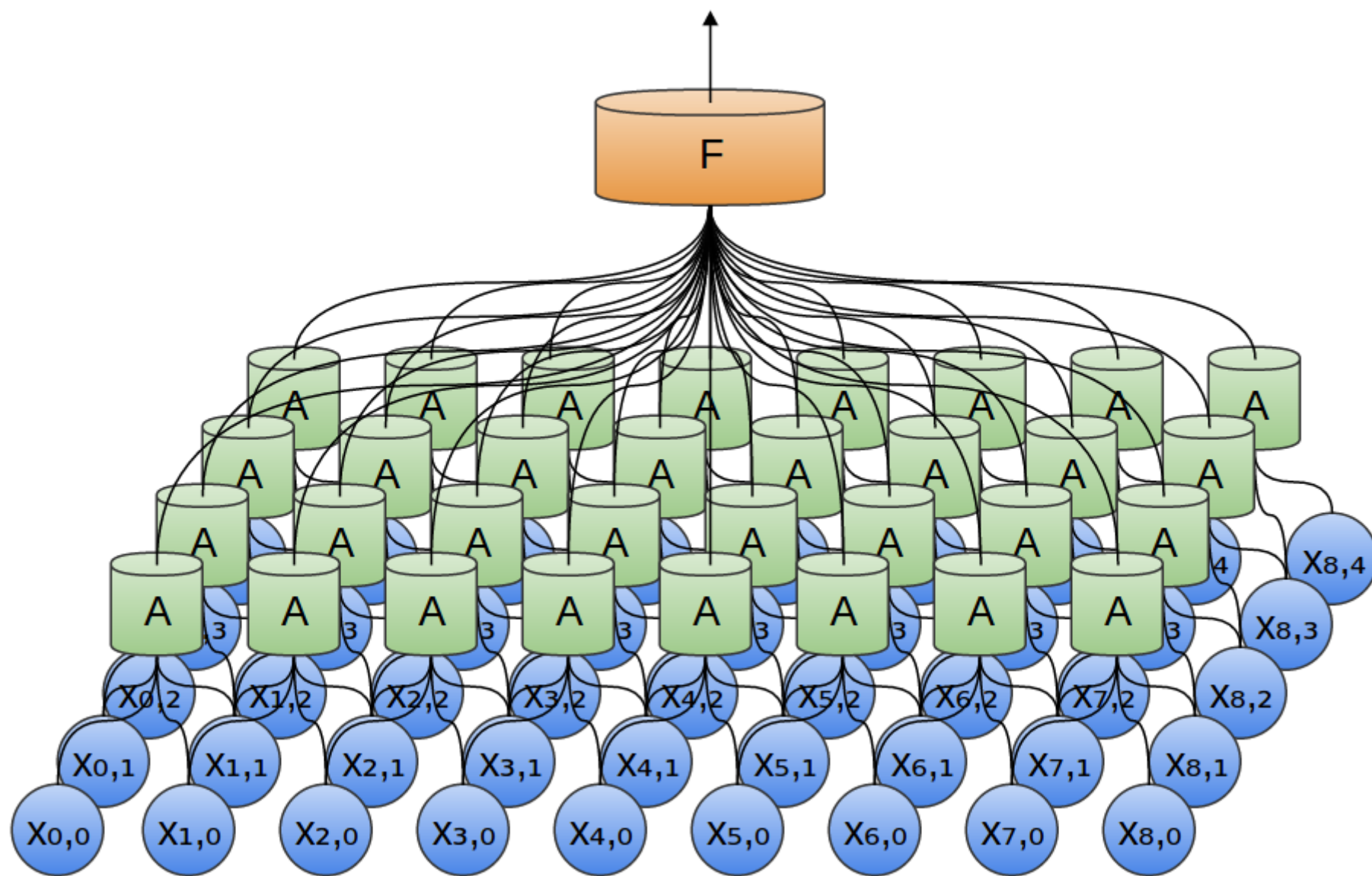
technology
idea digital upwards algorithms mind training
smartphone
concept
machine education data information learn
research
future
learning
recognizes
draws
intelligence
system
social drawing
screen smart
tech
internet
match
network
mobile
robot
massive
artificial
neural
computer
vivid
presentation
facial
learned
intellect

Weight Sharing (via convolution)

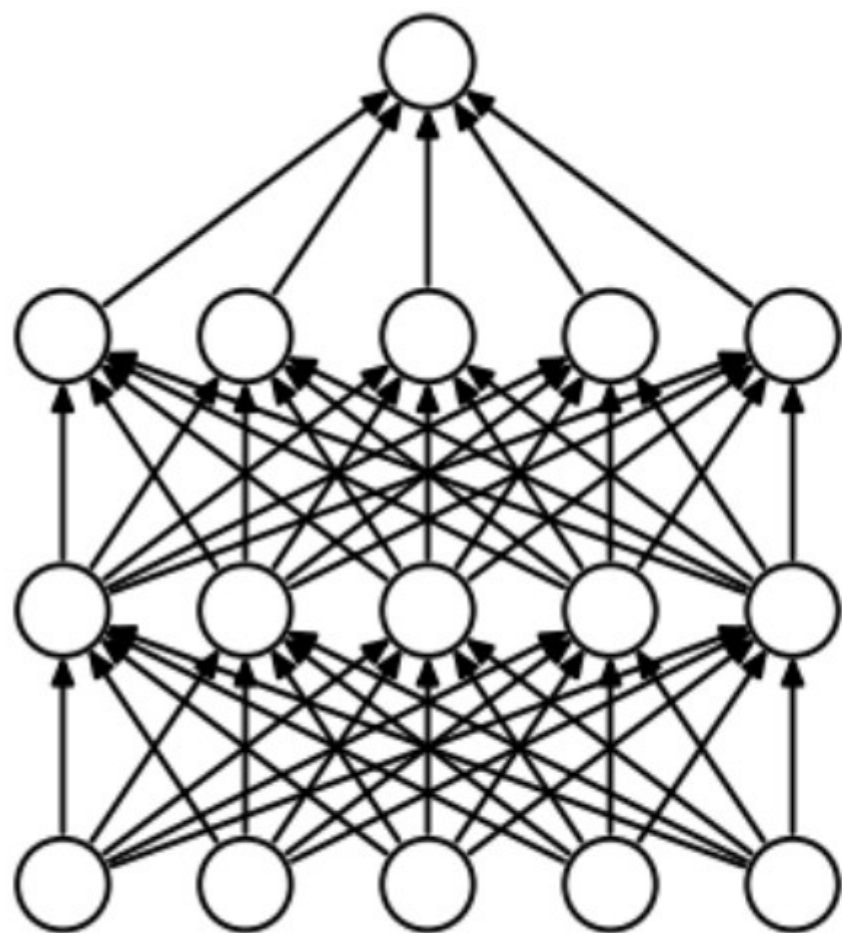




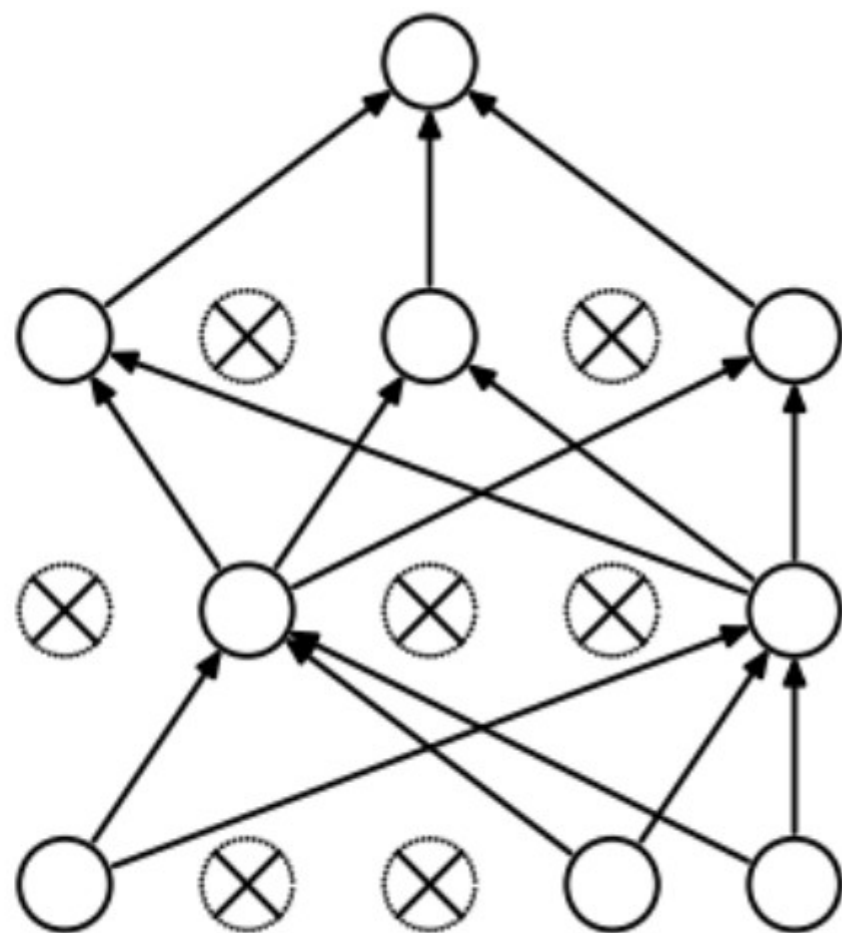




Dropout



(a) Standard Neural Net



(b) After applying dropout.