

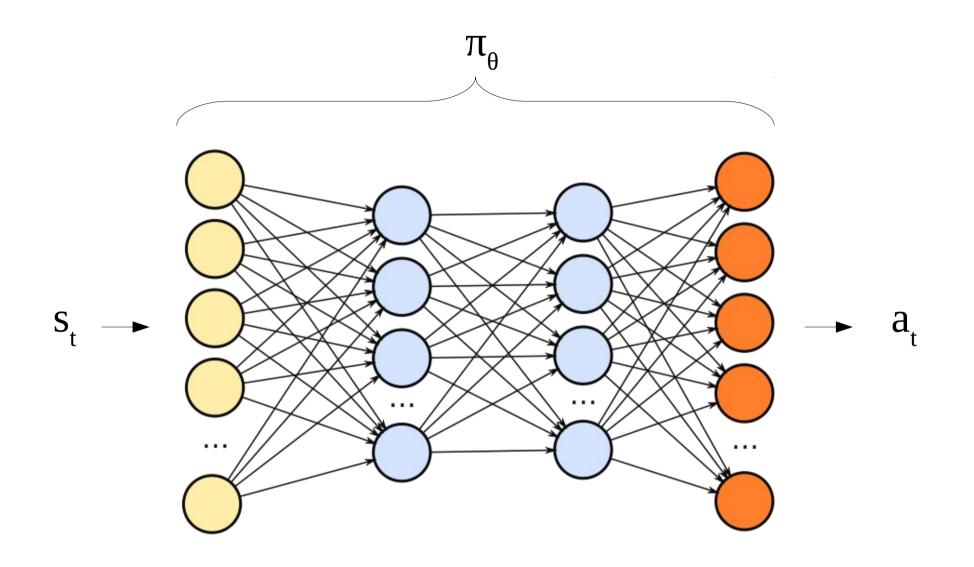
### **Introduction to Artificial Intelligence** COSC 4550 / COSC 5550

Professor Cheney 10/11/17

Q-learning is not easily extended to continuous action spaces (since you must iterate over actions)

what other methods could we use here?

## policy search



rather than try to learn value functions, let's just optimize the policy directly

make small changes to the policy ( $\theta$ + $\Delta$ ), and see if they improve the agent's cumulative rewards

## very similar in spirit to hillclimbing

most common variant is "Cross-Entropy Method" (uses importance sampling to estimate performance)

or we can try to approximate the gradients of the reward with respect to our parameters directly from rollouts

this assumes a stochastic policy (output is the probability to choosing some action)

thus we'll take lots of paths through the state space (making a different decision each time we come to a state) similar in spirit to our Monte Carlo Tree Search method for estimating value functions at each node (but now we're estimating value of a policy)

most popular variant in practice is "REINFORCE"

we've talked a lot about gradients, backpropogating error signals, learning models from the interactions of features

but up to now we've been kind of vague about these ideas

## machine learning!!!

$$y = f(x)$$

$$f(1) = 2f(4) = 8f(3) = 6f(5) = 10f(2) = 4$$

$$f(x) = 2^*x$$

$$y = f(x)$$

$$f(1) = 2f(2) = 4f(3) = 6f(4) = 8f(5) = 10$$

$$f(x) = 2^*x$$

$$y = f(x)$$

$$f(1) = 2f(2) = 3f(3) = 6f(4) = 11f(5) = 18$$

$$f(x) = x^2 - 2x + 3$$

$$y = f(x)$$

> f([T, F, T, F]) = T f([F, F, F, T]) = F f([T, T, F, F]) = T f([F, F, T, T]) = Ff([T, F, T, F]) = T

 $f([x_1, x_2, x_3, x_4]) = (x_1 \land x_2) \cup (x_3 \land \neg x_4)$ 

$$y = f(x)$$

reward<sub>t</sub> = valueFunction( state<sub>t</sub> )

person? = faceDetector( cameraSensor )

stockValue = valuationFunction( companyMetrics )

word? = speechRecognitionFunction( sounds )

graduateCollege? = predictorFunction( highSchoolGrades )

y = f(x)

"supervised learning" (where we are given examples of x and y pairs) (correct answer *y* is the supervision)

# "regression" (predict a real-valued number)

"classification" (choose which class will be true)

### decision trees

supervised learning method for when solutions are composed of "if" statements

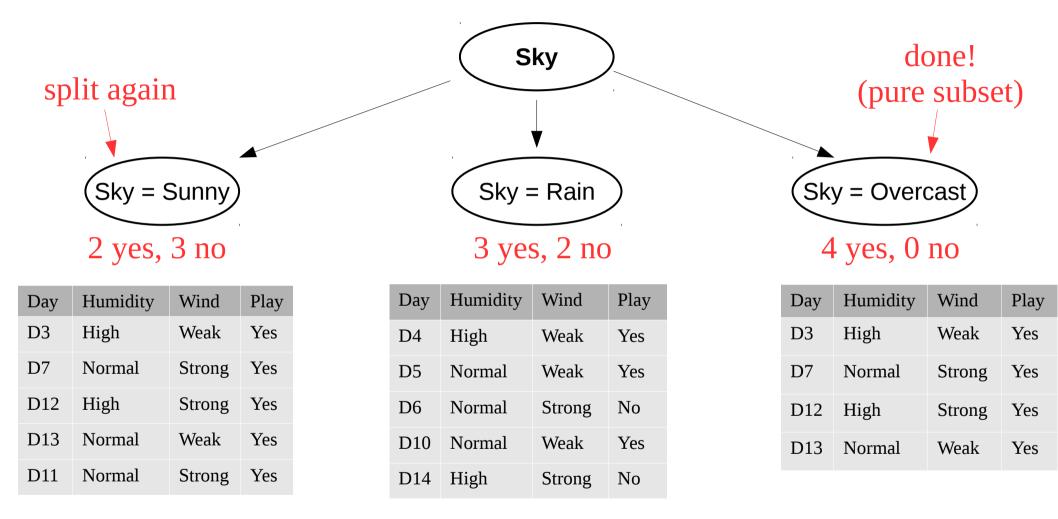
wearWinterHatToday? = f( weather )

f = "if it's cold, or if it's raining and if it's windy, but not if my hair is still wet"

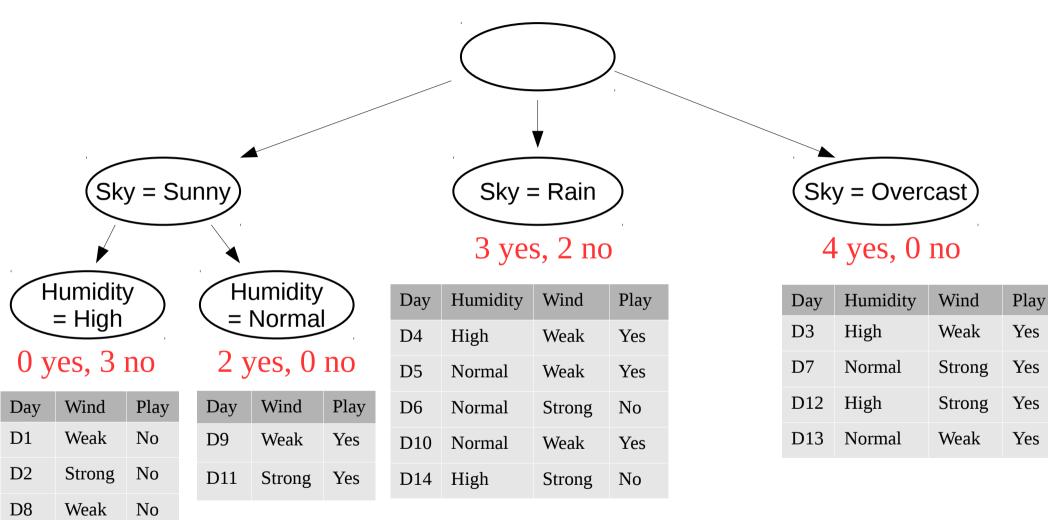
## on a given day, predict if John will play tennis or not?

Day	Sky	Humidity	Wind	Play	🔶 9 yes, 5 no
D1	Sunny	High	Weak	No	
D2	Sunny	High	Strong	No	
D3	Overcast	High	Weak	Yes	
D4	Rain	High	Weak	Yes	
D5	Rain	Normal	Weak	Yes	
D6	Rain	Normal	Strong	No	
D7	Overcast	Normal	Strong	Yes	
D8	Sunny	High	Weak	No	
D9	Sunny	Normal	Weak	Yes	
D10	Rain	Normal	Weak	Yes	
D11	Sunny	Normal	Strong	Yes	
D12	Overcast	High	Strong	Yes	
D13	Overcast	Normal	Weak	Yes	
D14	Rain	High	Strong	No	
D15	Rain	High	Weak	???	

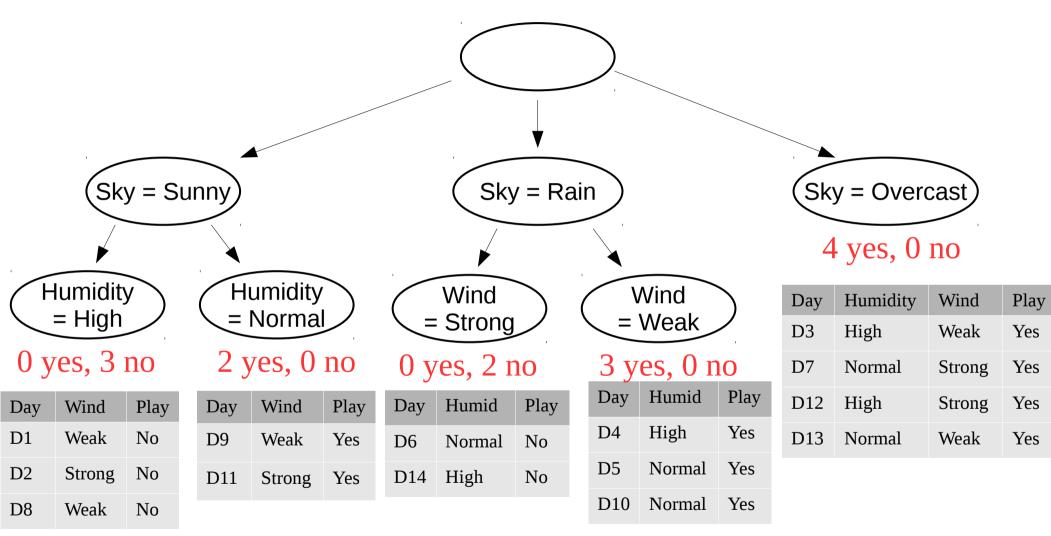
# 1) choose an attribute, and draw the tree with the subtable for each value of that attribute:



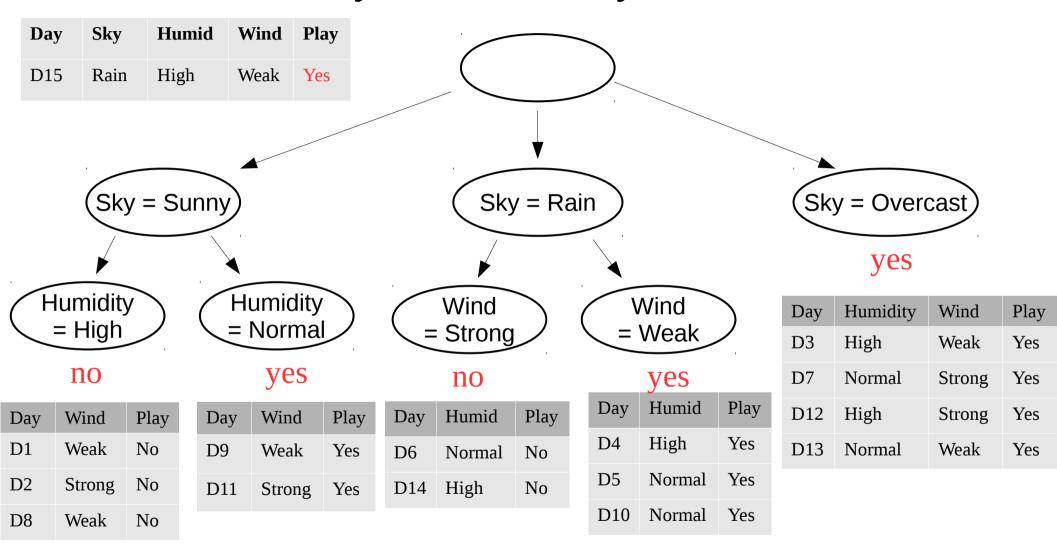
# 1) choose an attribute, and draw the tree with the subtable for each value of that attribute:



# 1) choose an attribute, and draw the tree with the subtable for each value of that attribute:



## "John will play tennis if it's overcast, or if it's raining but not windy, or if it's sunny but not humid"



but won't the tree (and the resulting logic) look different depending on what order we expand the nodes?

how did we know which node to expand first?

expand the attribute that would provide the most information! (reduce the most uncertainty)

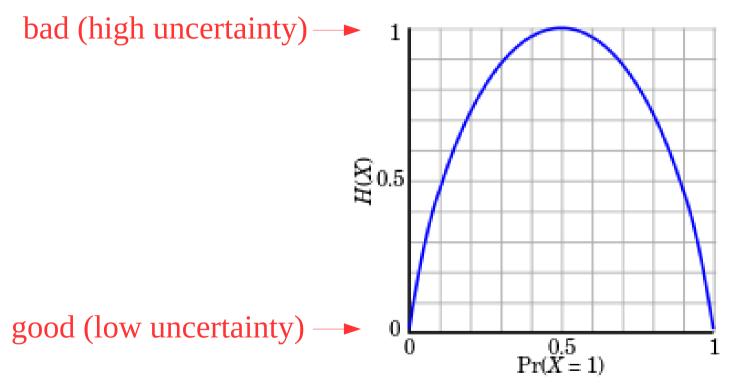
the information theoretic metric for uncertainty is entropy (H)!

$$H(V) = -\Sigma_{i=1:n} P(v_i) * \log_2(P(v_i))$$

e.g. (n  $\in \{T,F\}$ ): H = - P(v\_T)\*log\_2(P(v\_T)) - P(v\_F)\*log\_2(P(v\_F))

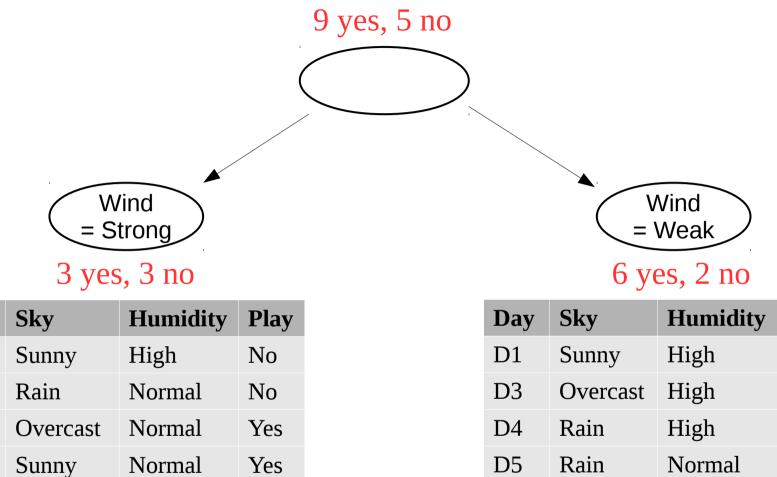


## $H(X) = P(X)*log_2(P(X))$



## on a given day, predict if John will play tennis or not?

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D12	Overcast	High	Strong	Yes	
D13	Overcast	Normal	Weak	Yes	
D14	Rain	High	Strong	No	



Day

D2

D6

D7

D11

D12

D14

Overcast

Rain

High

High

Yes

No

	Ounny
D3	Overcast
D4	Rain
D5	Rain
D8	Sunny

D9

D10

D13

Sunny

Overcast

Rain

Play

No

Yes

Yes

Yes

No

Yes

Yes

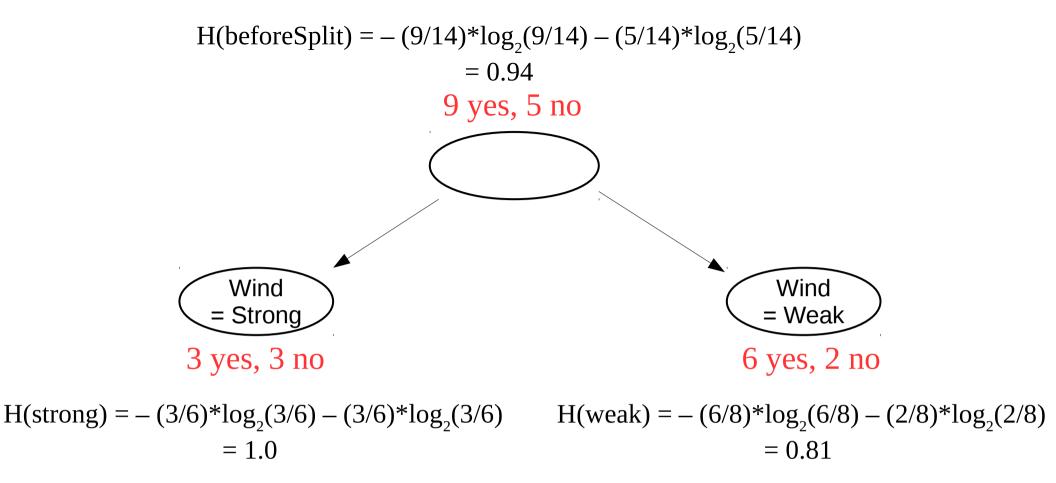
Yes

High

Normal

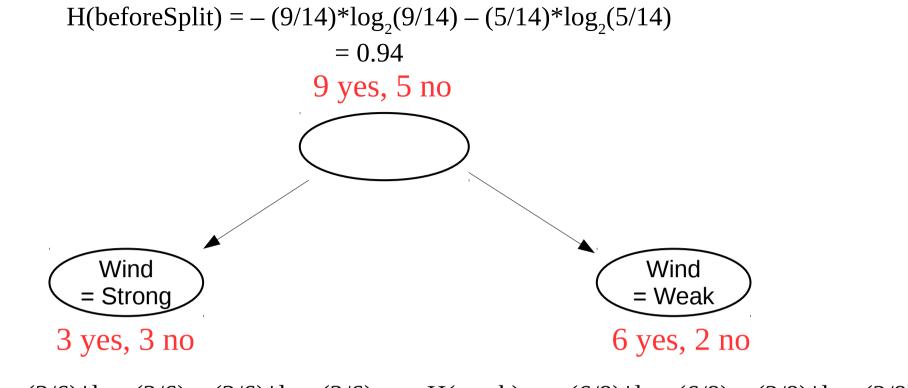
Normal

Normal



#### did this split help or hurt (and by how much)?

"information gain" is the entropy change in each subset after the split, weighted by the size of the subset



 $H(strong) = -(3/6)*\log_{2}(3/6) - (3/6)*\log_{2}(3/6) H(weak) = -(6/8)*\log_{2}(6/8) - (2/8)*\log_{2}(2/8) = 1.0$ = 0.81

information gain = H(beforeSplit) – 6/14 \*H(strong) – 8/14\*H(weak)

information gain = 0.94 – 6/14 \* 1.0 – 8/14 \* 0.81 = **0.049 bits** 

### now we have a way to recursively split datasets along different attributes

and we have a way to choose what order to split them

super simple! (yet effective)
frequently used in practice